



Andrei Andreyevich Markov  
1856–1922

1878 gold medal at St Petersburg University:  
*On the integration of differential equations by  
means of continued fractions.*

1880 Master's: *On the binary quadratic forms  
with positive determinant.*

1884 doctorate: *On certain applications of  
continued fractions.*

After 1900, Markov applied continued fractions, pioneered by Chebyshev, to probability theory.

## Axioms of Probability

Definition: A **sample space** is a set **S** together with a function **P** on subsets **A** of **S**, called **events**, such that:

- $P(A) \geq 0$ , for events  $A \subseteq S$ ,
- $P(S) = 1$ ,
- $P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$ , for countably many pairwise disjoint events  $A_1, A_2, \dots$

## Using Axioms to Prove Propositions

Proposition: For any events  $A$  and  $B$ ,

$$P(A \cup B) = P(A) + P(B) - P(A \cap B).$$

Proof: Notice  $A \cup B = A \cup (A^c \cap B)$ .

Since  $A$  and  $A^c \cap B$  are disjoint, the axioms give

$$P(A \cup B) = P(A) + P(A^c \cap B). \quad (1)$$

Notice also  $B = (A \cap B) \cup (A^c \cap B)$ .

Since  $A \cap B$  and  $A^c \cap B$  are disjoint, we have

$$P(B) = P(A \cap B) + P(A^c \cap B) \quad (2)$$

The Proposition follows from (1) and (2).

Note:  $P(A \cup B) = P(A) + P(B)$ , if  $A \cap B = \emptyset$ .

## Markov Model of Kitten Behavior

When we find a kitten napping we check back every fifteen minutes to record whether she is exploring, hunting or napping. If we check back 4 times, we might record

$$n, n, h, e, n.$$

A probability distribution on the sample space  $\{e, h, n\}^5$  is defined using a *transition matrix* and an *initial distribution*:

$$A = \begin{matrix} e \\ h \\ n \end{matrix} \begin{pmatrix} .4 & .2 & .1 \\ .3 & .6 & .1 \\ .3 & .2 & .8 \end{pmatrix} \quad \pi = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} P(nnhen) &= P(n)P(n|n)P(h|n)P(e|h)P(n|e) \\ &= 1 \cdot .8 \cdot .1 \cdot .2 \cdot .3 \\ &= .0048 \end{aligned}$$

What fraction of the time does she explore, hunt and nap?

$$\lim_{t \rightarrow \infty} A^t \pi = ?$$



	$t = 0$	$t = 1$	$t = 2$	$t = 3$	$t = 4$
explore	0	.1	.14	.159	.1690
hunt	0	.1	.17	.213	.2383
nap	1	.8	.69	.628	.5927

# Hidden Markov Models

Lynne Butler

Haverford College

**Def:** Let  $N, M > 0$ . A *Hidden Markov Model* is a triple  $(A, B, \pi)$ , where

$A = (a_{rq})_{\substack{r \in Q \\ q \in Q}}$  is an  $N \times N$  matrix,

$B = (b_{vq})_{\substack{v \in V \\ q \in Q}}$  is an  $M \times N$  matrix,

$\pi = (\pi_q)_{q \in Q}$  is an  $N \times 1$  vector.

All entries are nonnegative, and in each column the entries sum to 1.

These models are used in speech recognition, cryptology, finance, and genomics.

Elements of  $V$  are *observations*, and elements of  $Q$  are *states*.

The model defines a probability distribution on the sample space  $Q^T \times V^T$ , where  $T > 0$ . The *probability* of a state sequence  $(s_0, s_1, \dots, s_{T-1})$  and observation sequence  $(o_0, o_1, \dots, o_{T-1})$  is:

$$p(s, o) = \pi_{s_0} b_{o_0 s_0} \prod_{t=1}^{T-1} a_{s_t s_{t-1}} b_{o_t s_t}.$$

At any time  $t$ , we find  $b_{vq} = P(O_t = v | S_t = q)$  and  $a_{rq} = P(S_{t+1} = r | S_t = q)$ . So, when in state  $q$ , the probability of observing  $v$  is  $b_{vq}$  and the probability of transiting to state  $r$  is  $a_{rq}$ .

**Ex:** For sequences of characters observed in English text, let  $V = \{a, b, \dots, z, \_ \}$ . A 2-state model, obtained from a long training text, has:

$$A = \begin{pmatrix} .27 & .71 \\ .73 & .29 \end{pmatrix} \quad B = \begin{matrix} a \\ b \\ \vdots \\ e \\ f \\ g \\ \vdots \\ z \\ \_ \end{matrix} \begin{pmatrix} .136 & .000 \\ .000 & .024 \\ \vdots & \vdots \\ .202 & .000 \\ .000 & .032 \\ .007 & .023 \\ \vdots & \vdots \\ .000 & .001 \\ .336 & .015 \end{pmatrix} .$$

How would you interpret the states of this model?

What does the model say about English text?

**Ex:** For sequences of % changes in S&P, let  $V = \{d, dm, n, um, u\}$  for 1/3/50 to 2/24/07:

$$v = \begin{cases} d & \text{if } \% \leq -.0054004 \\ dm & \text{if } -.0054004 < \% \leq -.0010955 \\ n & \text{if } -.0010955 < \% \leq .0019845 \\ um & \text{if } .0019845 < \% \leq .0060816 \\ u & \text{if } .0060816 < \% \end{cases} .$$

Bins are defined to capture equal numbers of observations.

How might you expect to interpret the states in a 2-state HMM?

Using code written by Alden Walker, Haverford math major Sumana Shrestha found:

$$A = \begin{pmatrix} .9933 & .0075 \\ .0067 & .9925 \end{pmatrix} \quad B = \begin{matrix} d \\ dm \\ n \\ um \\ u \end{matrix} \begin{pmatrix} .125 & .283 \\ .228 & .169 \\ .264 & .129 \\ .243 & .153 \\ .140 & .266 \end{pmatrix} .$$

To find the 2-state model that best fits given data, use the EM algorithm (also known as the Baum-Welch or forward-backward algorithm).

See “A tutorial on hidden Markov models and selected applications in speech recognition” by Rabiner, published in Proceedings of the IEEE.