# Rank-one ECS manifolds of dilational type 

Andrzej Derdzinski and Ivo Terek


#### Abstract

We study ECS manifolds, that is, pseudo-Riemannian manifolds with parallel Weyl tensor which are neither conformally flat nor locally symmetric. Every ECS manifold has rank 1 or 2 , the rank being the dimension of a distinguished null parallel distribution discovered by Olszak, and a rank-one ECS manifold may be called translational or dilational, depending on whether the holonomy group of a natural flat connection in the Olszak distribution is finite or infinite. Some such manifolds are in a natural sense generic, which refers to the algebraic structure of the Weyl tensor. Various examples of compact rank-one ECS manifolds are known: translational ones (both generic and nongeneric) in every dimension $n \geq 5$, as well as odd-dimensional nongeneric dilational ones, some of which are locally homogeneous. As we show, generic compact rank-one ECS manifolds must be translational or locally homogeneous, provided that they arise as isometric quotients of a specific class of explicitly constructed "model" manifolds. This result is relevant since the clause starting with "provided that" may be dropped: according to a theorem which we prove in another paper, the models just mentioned include the isometry types of the pseudo-Riemannian universal coverings of all generic compact rank-one ECS manifolds. Consequently, all generic compact rank-one ECS manifolds are translational.


## 1. Introduction

By ECS manifolds [3] one means those pseudo-Riemannian manifolds of dimensions $n \geq 4$ which have parallel Weyl tensor, but not for one of two obvious reasons: conformal flatness or local symmetry. Both their existence, for every $n \geq 4$, and indefiniteness of their metrics, are results of Roter [13, Corollary 3], [2, Theorem 2]. Their local structure has been completely described in [4].

The acronym "ECS" stands for essentially conformally symmetric. On every ECS manifold $(M, g)$ there exists a naturally distinguished null parallel distribution $\mathscr{D}$, known as the Olszak distribution [12], [4, p. 119]. Its dimension, necessarily equal to 1 or 2 , is referred to as the rank of $(M, g)$. We call a rank-one ECS manifold
translational, or dilational, when the holonomy group of the flat connection in $\mathfrak{D}$, induced by the Levi-Civita connection, is finite or, respectively, infinite.

Examples of compact rank-one ECS manifolds are known [5,6] to exist for every dimension $n \geq 5$. They are all geodesically complete, translational, and none of them is locally homogeneous. Quite recently [8] we constructed dilational type compact rank-one ECS manifolds, including locally-homogeneous ones, in all odd dimensions $n \geq 5$. It remains an open question whether a compact ECS manifold may have rank two, or be of dimension four.

In Section 4 we describe specific rank-one ECS model manifolds [13, p. 93], representing all dimensions $n \geq 4$ and all indefinite metric signatures. Some of them are generic, which refers to a self-adjoint linear endomorphism $A$ of a pseudo-Euclidean vector space used in constructing the model manifold, and means that there are only finitely many linear isometries commuting with $A$. (In Remark 4.4 we point out that this genericity is an intrinsic geometric property of the metric, and not just a condition imposed on the construction.)

The dilational examples of [8], mentioned earlier, are all nongeneric, while among the translational ones in [5,6], some are generic, and others are not, which raises an obvious question: Can a dilational type compact rank-one ECS manifold be generic? Theorem C of the present paper, combined with results of [9] mentioned below, answers this question in the negative:
all generic compact rank-one ECS manifolds are translational.
Here are some details. Since the Olszak distribution $\mathscr{D}$ is a real line bundle over the compact rank-one ECS manifold in question, the holonomy group $K$ of the flat connection in $\mathscr{D}$ induced by the Levi-Civita connection is a countable multiplicative subgroup of $\mathbb{R} \backslash\{0\}$ (see Section 2), and we will repeatedly refer to
the positive holonomy group $K_{+}=K \cap(0, \infty)$ of the flat connection in $\mathcal{D}$. (1.2)

Our first main result, established in Section 9, can be stated as follows.
Theorem A. In a generic compact isometric quotient of a rank-one ECS model manifold, the group $K_{+}$in (1.2) is not infinite cyclic.

The next fact, which we prove at the very end of Section 3, holds in a more abstract setting, with no reference to either genericity or model manifolds.

Theorem B. Given a compact rank-one ECS manifold ( $M, g$ ), with $K_{+}$in (1.2) not infinite cyclic, $K_{+}$may be trivial, which makes $(M, g)$ translational, or else $K_{+}$is dense in $(0, \infty)$, and then $(M, g)$ must be locally homogeneous.

The third result trivially follows from Theorems A and B.
Theorem C. Every generic compact isometric quotient of a rank-one ECS model manifold is either translational or locally homogeneous.

In the locally-homogeneous case the group (1.2) is dense in $(0, \infty)$.
According to the final clause of our Theorem 3.3, compact locally homogeneous rank-one ECS manifolds are necessarily dilational. Theorem C thus has the following consequence.

Corollary D. For a generic compact rank-one ECS manifold arising as an isometric quotient of a model manifold, the property of being dilational is equivalent to local homogeneity.

Both Theorem C and Corollary D do not really require assuming that the manifold is an isometric quotient of a model. Namely, as we show in [9, Corollary D], the pseu-do-Riemannian universal covering of any generic compact rank-one ECS manifold is necessarily isometric to one of the model manifolds.

Furthermore, according to another result of the same paper [9, Theorem E], a generic compact rank-one ECS manifold cannot be locally homogeneous. Thus, the final clause of our Theorem C is actually vacuous, and (1.1) follows. However, Theorem C, precisely as stated here, is a crucial step in the arguments of [9].

The paper is organized as follows. Sections 3 and 4, dealing with rank-one ECS manifolds, are followed by some material from linear algebra and algebraic number theory (genericity of nilpotent self-adjoint linear endomorphisms of pseudo-Euclidean spaces, and the cyclic root-group condition for $\operatorname{GL}(\mathbb{Z})$-polynomials), in Sections 5 and 7. Those two are separated by a section devoted to subspaces of certain spaces $\mathcal{E}$ of vector-valued functions on $(0, \infty)$, invariant under an operator $C T: \mathcal{E} \rightarrow \mathcal{E}$ which is relevant to the existence question for generic compact isometric quotients of rank-one ECS model manifolds. After Section 8, presenting a combinatorial argument (Theorem 8.1) needed to establish Theorem A, comes the final Section 9, where we prove Theorem A by contradiction, assuming that its hypotheses hold and yet $K_{+}$in (1.2) is infinite cyclic. Lemma 9.2 provides the first important consequence of this assumption: the existence of a $C T$-invariant vector subspace, of the type discussed in Section 6, with the additional properties (9.5). Such a subspace necessarily satisfies further conditions, listed in Lemma 9.4, and leading - for reasons stated at the very end of Section 9 - to a combinatorial structure, the existence of which contradicts Theorem 8.1.

## 2. Preliminaries

Unless stated otherwise, manifolds and mappings are smooth, the former connected. The group $\operatorname{Aff}(\mathbb{R})$ of affine transformations $t \mapsto q t+p$ of $\mathbb{R}$, with real $p$ and $q \neq 0$, has the index-two subgroup $\operatorname{Aff}^{+}(\mathbb{R})=\{(q, p) \in \operatorname{Aff}(\mathbb{R}): q>0\}$, and

$$
\begin{equation*}
\text { nontrivial finite subgroups of } \operatorname{Aff}(\mathbb{R}) \text { have the form }\{(1,0),(-1,2 c)\} \tag{2.1}
\end{equation*}
$$

with any center $c \in \mathbb{R}$ of the reflection $(-1,2 c)$. In fact, the square of any $(q, p)$ in such a subgroup $\Xi$ lies in the intersection $\Xi \cap \operatorname{Aff}^{+}(\mathbb{R})$, which due to its finiteness must consist of translations, and hence be trivial.

Every $(q, p) \in \operatorname{Aff}^{+}(\mathbb{R}) \backslash\{(1,0)\}$ is either a translation $(q=1)$, or has a unique fixed point $c$ (and then we call it a dilation with center $c$, since by choosing $c$ as the new origin we turn $c$ into 0 and $(q, p)$ into $(q, 0))$. Now,

> any Abelian subgroup of $\mathrm{Aff}^{+}(\mathbb{R})$ consists of translations, or of dilations with a single center,
as two commuting self-mappings of a set preserve each other's fixed-point sets, and so in $\mathrm{Aff}^{+}(\mathbb{R}) \backslash\{(1,0)\}$ two dilations with different centers cannot commute with each other or with a translation.

Lemma 2.1. Let $(\cdot, \cdot)$ be a symmetric bilinear form in a real vector space. If a coset $S$ of a $(\cdot, \cdot)$-null one-dimensional subspace $Q$ is not contained in the $(\cdot, \cdot)$-orthogonal complement of $Q$, then $S$ contains a unique $(\cdot, \cdot)$-null vector.

In fact, $S$ is parametrized by $t \mapsto x=v+t u$, where $u$ spans $Q$ and $(v, u) \neq 0$, so that $(x, x)=(v, v)+2 t(v, u)$ vanishes for a unique $t \in \mathbb{R}$.

Let a group $\Gamma$ act on a manifold $\widehat{M}$ freely by diffeomorphisms. One calls the action of $\Gamma$ properly discontinuous if there exists a locally diffeomorphic surjective mapping $\pi: \widehat{M} \rightarrow M$ onto some manifold $M$ such that the $\pi$-preimages of points of $M$ coincide with the orbits of the $\Gamma$ action. One then refers to $M$ as the quotient of $\widehat{M}$ under the action of $\Gamma$ and writes $M=\widehat{M} / \Gamma$.

For $\pi, \widehat{M}, M, \Gamma$ as above and a flat linear connection $\nabla$ in a vector bundle $\mathcal{Z}$ over $M$, let $\widehat{Z}$ and $\widehat{\nabla}$ be the $\pi$-pullbacks of $\mathcal{Z}, \nabla$ to $\widehat{M}$. If $\widehat{M}$ is also simply connected, the vector space $\mathcal{F}$ of all $\widehat{\nabla}$-parallel sections of $\widehat{Z}$ trivializes $\widehat{Z}$, and a homomorphism $\Gamma \rightarrow \mathrm{GL}(\mathcal{F})$, known as the holonomy representation of $\nabla$, assigns to $\gamma \in \Gamma$ the composite isomorphism

$$
\begin{equation*}
\mathcal{F} \rightarrow \hat{Z}_{y} \rightarrow \mathcal{Z}_{x} \rightarrow \hat{Z}_{\gamma(y)} \rightarrow \mathcal{F} \tag{2.3}
\end{equation*}
$$

described with the aid of any given $y \in \widehat{M}$ and $x=\pi(y)$, where the two middle arrows denote the identity automorphism of $\hat{Z}_{y}=\mathcal{Z}_{x}=\widehat{Z}_{\gamma(y)}$, and the first/last one is the evaluation operator or its inverse. Note that (2.3) does not depend on the choice
of $y \in \widehat{M}$, being locally (and hence globally) constant as a function of $y$. To see this, we choose connected neighborhoods $\widehat{U}$ of $y$ in $\widehat{M}$ and $U$ of $x=\pi(y)$ in $M$ such that $Z$ restricted to $U$ is trivialized by the space $\mathscr{F}_{U}$ of its $\nabla$-parallel sections and $\pi$ maps $\widehat{U}$ diffeomorphically onto $U$. The isomorphism $\mathcal{F} \rightarrow \mathcal{F}_{U}$ arising as the restriction to $\widehat{U}$ followed by the "identity" identification via $\pi$ then allows us to apply (2.3) to a fixed section from $\mathcal{F}$, using all $y \in \widehat{U}$ at once.

When $\mathbb{Z}$ is a real line bundle, with the multiplicative $\operatorname{group} \operatorname{GL}(\mathcal{F})=\mathbb{R} \backslash\{0\}$,
for any $x \in M$, the image of the holonomy representation

$$
\begin{equation*}
\Gamma \rightarrow \mathbb{R} \backslash\{0\} \text { coincides with the holonomy group of } \nabla \text { at } x, \tag{2.4}
\end{equation*}
$$

the latter meaning the group of the $\nabla$-parallel transports $\mathbb{Z}_{x} \rightarrow \mathbb{Z}_{x}$ along all the loops at $x$. In fact, if (2.3) assigns to $\gamma \in \Gamma$ the multiplication by $q \in \mathbb{R} \backslash\{0\}$ and $y \in \pi^{-1}(x)$ is fixed, the $\nabla$-parallel transport $\Theta$ along the $\pi$-image of any curve joining $y$ to $\gamma(y)$ in $\widehat{M}$ is $\mathcal{F} \leftarrow \hat{Z}_{y} \leftarrow Z_{x}$ followed by $\mathrm{Id}_{\mathscr{F}}$ followed by $\mathcal{Z}_{x} \leftarrow \hat{Z}_{\gamma(y)} \leftarrow \mathscr{F}$, the reversed arrows representing the inverses of those in (2.3). Writing $\operatorname{Id}_{\mathcal{F}}$ as $q^{-1}$ times (2.3), we get $\Theta$ equal to $q^{-1}$ times the identity of $\mathcal{Z}_{x}$.
Lemma 2.2. Suppose that $q \in \mathbb{R} \backslash\{1,-1\}$ and a diffeomorphism $\gamma \in \operatorname{Diff} \widehat{M}$ of a manifold $\widehat{M}$ pushes a complete nontrivial vector field $w$ forward onto $q w$. If $\mathbb{R} \ni t \mapsto$ $\phi(t, \cdot) \in \operatorname{Diff} \widehat{M}$ denotes the flow of $w$, while a subgroup $\Gamma \subseteq \operatorname{Diff} \widehat{M}$ contains $\gamma$ and $\phi(t, \cdot)$ for some $t \neq 0$, then the action of $\Gamma$ on $\widehat{M}$ cannot be properly discontinuous.

Proof. The $k$ th iteration $\gamma^{k}$ of $\gamma$, for $k \in \mathbb{Z}$, pushes $w$ forward onto $q^{k} w$, giving $\gamma^{k} \circ \phi(t, \cdot)=\phi\left(q^{k} t, \cdot\right) \circ \gamma^{k}$ for all $t$ and all $k \in \mathbb{Z}$, so that $\phi\left(q^{k} t, \cdot\right) \in \Gamma$ with our fixed $t$. Choosing $x \in \widehat{M}$ such that $w_{x} \neq 0$, and setting $\eta=\operatorname{sgn}(1-|q|)$, we thus get a sequence $\phi\left(q^{\eta k} t, x\right)$ with mutually distinct terms when $k$ is large, tending to $x$ as $k \rightarrow \infty$, which obviously precludes proper discontinuity.

The conclusion of Lemma 2.2 remains valid when, instead of $\phi(q t, \cdot) \in \Gamma$ for some $t$, one assumes periodicity of the flow of $w$, while replacing the condition $\gamma, \phi(t, \cdot) \in \Gamma$ with just $\gamma \in \Gamma$ (and then using $t$ equal to the period of the flow).

Remark 2.3. A submersion from a compact manifold into a connected manifold is a bundle projection, which is the compact case of Ehresmann's fibration theorem [10, Corollary 8.5.13].

## 3. Compact rank-one ECS manifolds

Throughout this section, $(\widehat{M}, \widehat{g})$ is the pseudo-Riemannian universal covering space of a compact rank-one ECS manifold $(M, g)$ of dimension $n \geq 4$, defined as in the Introduction, $\mathscr{D}$ stands for the (one-dimensional, null, parallel) Olszak distribution
on $(M, g)$, and $\mathscr{D}^{\perp}$ for its orthogonal complement, while $\widehat{\mathscr{D}}, \widehat{\mathscr{D}}^{\perp}$ are the analogous distributions on $(\widehat{M}, \widehat{g})$. Thus, $M=\widehat{M} / \Gamma$ for a subgroup $\Gamma$ of the full isometry group $\operatorname{Iso}(\widehat{M}, \widehat{g})$ isomorphic to the fundamental group of $M$, and acting on $\widehat{M}$ freely and properly discontinuously via deck transformations. The connection in $\widehat{\mathscr{D}}$ induced by the Levi-Civita connection $\widehat{\nabla}$ of $(\widehat{M}, \widehat{g})$ is always flat [7, Sect. 10]. Thus, due to simple connectivity of $\widehat{M}$,

$$
\begin{align*}
& \widehat{\mathscr{D}} \text { is spanned by the parallel gradient } \\
& \widehat{\nabla} t \text { of a surjective function } t: \widehat{M} \rightarrow I \tag{3.1}
\end{align*}
$$

onto an open interval $I \subseteq \mathbb{R}$ (which is the case even without assuming the existence of a compact quotient). The Olszak distribution being a local geometric invariant of the ECS metric in question [4, Sect. 2], (3.1) determines $\widehat{\nabla} t$ and $t$ uniquely up to multiplication by nonzero constants and, respectively, affine substitutions, meaning replacements of $t$ with $q t+p$, where $(q, p) \in \operatorname{Aff}(\mathbb{R})$ (for $\operatorname{Aff}(\mathbb{R})$ as in Section 2: $q, p \in \mathbb{R}$ and $q \neq 0$ ). Consequently, we have group homomorphisms

$$
\begin{align*}
& \operatorname{Iso}(\widehat{M}, \widehat{g}) \ni \gamma \mapsto(q, p) \in \operatorname{Aff}(\mathbb{R}),  \tag{3.2a}\\
& \operatorname{Iso}(\widehat{M}, \widehat{g}) \ni \gamma \mapsto q \in \mathbb{R} \backslash\{0\} \tag{3.2b}
\end{align*}
$$

characterized, for any $\gamma \in \operatorname{Iso}(\widehat{M}, \widehat{g})$, by $t \circ \gamma=q t+p$ and $\gamma^{*} d t=q d t$, that is,

$$
\begin{equation*}
(d \gamma) \widehat{\nabla} t=q^{-1} \widehat{\nabla} t \tag{3.3}
\end{equation*}
$$

According to [7, formula (6.4) and the end of Sect. 12],

$$
\begin{align*}
& \widehat{D}^{\perp}=\operatorname{Ker} d t \text {, the levels of } t: \widehat{M} \rightarrow I \text { are all } \\
& \text { connected and coincide with the leaves of } \widehat{\mathscr{D}}^{\perp} . \tag{3.4}
\end{align*}
$$

Lemma 3.1. The above hypotheses imply that the image of $\Gamma$ under (3.2a) is infinite, while its image under (3.2b) coincides with the holonomy group of the flat connection in $D$.

Proof. The first image, if finite, would lie within some $\{(1,0),(-1,2 c)\}$, cf. (2.1), causing $(t-c)^{2}$ to descend to a nonconstant function with at most one critical value on the compact manifold $M$. The second claim follows from (2.4): by (3.1) and (3.3), the action (2.3) of any $\gamma \in \Gamma$ on the parallel section $\widehat{\nabla} t$ spanning $\widehat{\mathscr{D}}$ equals the multiplication by the corresponding $q^{-1}$. Namely, the two middle arrows in (2.3) now are restrictions of $d \pi_{y}$ and $\left[d \pi_{\gamma(y)}\right]^{-1}$, so that their composite $\hat{Z}_{y} \rightarrow \mathcal{Z}_{x} \rightarrow \hat{Z}_{\gamma(y)}$ equals $d \gamma_{y}$. (From $\pi \circ \gamma=\pi$ we get $d \pi_{\gamma(y)} \circ d \gamma_{y}=d \pi_{y}$.) Thus, (2.3) takes $w=$ $\widehat{\nabla} t$ first to $w_{y}$, then (two successive arrows) to $d \gamma_{y} w_{y}$ which - by (3.3) - equals $q^{-1} w_{\gamma(y)}$, the evaluation at $\gamma(y)$ of $q^{-1} w$.

The translational/dilational dichotomy of the Introduction, meaning finiteness/infiniteness of the holonomy group of the flat connection in $\mathscr{D}$ induced by the LeviCivita connection of $g$, can now be summarized in terms of the homomorphism (3.2b) restricted to $\Gamma$. Specifically, by Lemma 3.1, the two cases are

$$
\begin{array}{r}
\text { translational: }|q|=1 \text { for each } \gamma \in \Gamma, \\
\text { dilational: }|q| \neq 1 \text { for some } \gamma \in \Gamma . \tag{3.5b}
\end{array}
$$

Lemma 3.2. With the assumptions and notations as above,
(a) the parallel vector field $\widehat{\nabla} t$ on $\widehat{M}$, spanning $\widehat{\mathcal{D}}$, is complete,
(b) in case (3.5b), $\phi(t, \cdot) \notin \Gamma$ for all $t \in \mathbb{R} \backslash\{0\}$, $\mathbb{R} \ni t \mapsto \phi(t, \cdot) \in \operatorname{Diff} \widehat{M}$ being the flow of $\widehat{\nabla} t$.

In fact, (a) appears in [7, the second italicized conclusion in Sect. 12], while (b) follows from (a) and Lemma 2.2 combined with (3.3).

The remainder of this section uses the assumptions preceding (3.1) along with

$$
\begin{equation*}
\text { transversal orientability of } \mathscr{D}^{\perp} \text { which, by (3.4), reads } \Gamma \subseteq \operatorname{Iso}^{+}(\widehat{M}, \widehat{g}) \tag{3.6}
\end{equation*}
$$

for the normal subgroup $\operatorname{Iso}^{+}(\widehat{M}, \widehat{g})$ forming the (3.2b)-preimage of $(0, \infty)$. This can always be achieved by replacing $(M, g)$ (or, $\Gamma$ ) with a two-fold isometric covering (or, an index-two subgroup), and has an obvious consequence: the translational case then means precisely that the holonomy group is trivial.

Theorem 3.3. In the dilational case (3.5b), with (3.6), the image of $\Gamma$ under (3.2a) consists of dilations with a single center. The replacement of $t$ in (3.1) by a suitable affine function of $t$ then makes this center appear as $t=0$, the interval I as $(0, \infty)$, and all $(q, p)$ in the (3.2a)-image of $\Gamma$ as having $p=0$.

Then the image of $\Gamma$ under (3.2a), always an infinite multiplicative subgroup of $(0, \infty)$, must be infinite cyclic unless $(\widehat{M}, \widehat{g})$ is locally homogeneous. On the other hand, (3.5b) follows if one assumes local homogeneity of $(\widehat{M}, \widehat{g})$.

Proof. As shown in [7, the beginning of Sect. 12], (3.6) implies the existence of a $C^{\infty}$ function $\psi: \widehat{M} \rightarrow(0, \infty)$ such that the 1 -form $\psi d t$ is $\pi$-projectable onto $M$ (in other words, $\Gamma$-invariant), and closed. According to (3.4), the $t$-levels in $\widehat{M}$ are all connected, and so closedness of $\psi d t$ makes $t$ globally a function of $t$, with $\psi=\chi \circ t$ for some $C^{\infty}$ function $\chi: I \rightarrow(0, \infty)$. A fixed antiderivative $\phi$ of $\chi$ thus constitutes a strictly increasing $C^{\infty}$ diffeomorphism $\phi: I \rightarrow J$ onto some open interval $J \subseteq \mathbb{R}$, while $\Gamma$-invariance of $d(\phi \circ t)=\psi d t$ means that $\Gamma$ acts on $\phi \circ t$ by translations: $\phi \circ t \circ \gamma=\phi \circ t+a$ with constants $a \in \mathbb{R}$ depending on $\gamma \in \Gamma$. The mappings $t: \widehat{M} \rightarrow I$ and $\phi \circ t: \widehat{M} \rightarrow J$ are $\Gamma$-equivariant relative to $\Gamma$ acting on $I$ and $J$
via the homomorphisms (3.2a), restricted to $\Gamma$, and $\gamma \mapsto a$. As the diffeomorphism $\phi: I \rightarrow J$ makes the two mappings equivariantly equivalent, the two homomorphisms have the same kernel $\Sigma \subseteq \Gamma$, leading to an isomorphism $(q, p) \mapsto \gamma \Sigma \mapsto a$ between the images of the two homomorphisms. The former image must thus be Abelian (as that of $\gamma \mapsto a$ is a group of translations) and so, due to (3.5b) and (2.2), it consists of dilations with a single center. An affine substitution of $t$ turns this center into 0 , and elements of the (3.2a)-image of $\Gamma$ into pairs ( $q, p$ ) with $q>0$ and $p=0$. As a result, for our open interval $I$,
(i) 0 lies in the closure of $I$, but not in $I$ itself.

The first claim of (i) is obvious: by (3.5b)-(3.6), for some $q \in(0, \infty) \backslash\{1\}$,
(ii) $I$ is closed under multiplications by powers of $q$ with integer exponents.

To verify the second one, note that, as shown in [7, formulae (6.6)-(6.8)], some nonconstant $C^{\infty}$ function $f: \widehat{M} \rightarrow \mathbb{R}$ has
(iii) $f \circ \gamma=q^{-2} f$ for all $\gamma \in \Gamma$ and $(q, p) \in \operatorname{Aff}^{+}(\mathbb{R})$ with $t \circ \gamma=q t+p$.

This $f$ is also globally a function of $t$ [7, the end of Sect. 12]. Treating $f$, informally, as a function $I \rightarrow \mathbb{R}$, and noting that all $(q, p)$ in the (3.2a)-image of $\Gamma$ now have $q>0$ and $p=0$, we get $f(t)=q^{2} f(q t)$ for such $q$, while these $q$, due to Lemma 3.1, form an infinite subgroup of $(0, \infty)$. Thus, $0 \notin I$, or else, fixing any $t$ in the equality $f(t)=$ $q^{2} f(q t)$ and letting $q \rightarrow 0$, we would get $f(t)=0$, even though $f$ is nonconstant.

By (i) and (ii), $I$ equals $(0, \infty)$ or $(-\infty, 0)$ and, replacing $t$ with $-t$ if necessary, we get $I=(0, \infty)$, proving the first assertion of the theorem.

To establish the second one, suppose that the (3.2a)-image of $\Gamma$, infinite as a consequence of Lemma 3.1, is not cyclic. This makes the image dense in $(0, \infty)$, so that, from continuity of $f$, our equation $f(t)=q^{2} f(q t)$ holds for all $t, q \in(0, \infty)$. Setting $t=1$, we get $f(q)=f(1) / q^{2}$. The resulting linearity of the function $|f|^{-1 / 2}$ amounts - see [7, Theorem 7.3] - to local homogeneity of $(\widehat{M}, \widehat{g})$.

Finally, suppose that $(\widehat{M}, \widehat{g})$ is locally homogeneous. The preceding lines now yield linearity of $|f|^{-1 / 2}$, that is, $f(t)=f(1) / t^{2}$ for all $t \in(0, \infty)$, and so $f$ is unbounded on $(0, \infty)$. This gives (3.5b), since (3.5a) would, by (iii), imply $\Gamma$-invariance of $f$, leading to its boundedness, as $M=\widehat{M} / \Gamma$ is compact.

Proof of Theorem B. Due to Lemma 3.1 we may, without loss of generality, assume (3.5b) and (3.6). Our claim now follows from Theorem 3.3.

## 4. The rank-one ECS model manifolds

In this section, we fix the data $f, I, n, V,\langle\cdot, \cdot\rangle, A$ consisting of an integer $n \geq 4$, a real vector space $V$ of dimension $n-2$, a pseudo-Euclidean inner product $\langle\cdot, \cdot\rangle$ on $V$, a nonzero, traceless, $\langle\cdot, \cdot\rangle$-self-adjoint linear endomorphism $A$ of $V$, and a nonconstant $C^{\infty}$ function $f: I \rightarrow \mathbb{R}$ on an open interval $I \subseteq \mathbb{R}$.

Treating $\langle\cdot, \cdot\rangle$ as a flat (constant) metric on $V$, and following [13], we define the simply connected $n$-dimensional pseudo-Riemannian manifold

$$
\begin{equation*}
(\widehat{M}, \widehat{g})=\left(I \times \mathbb{R} \times V, \kappa d t^{2}+d t d s+\langle\cdot, \cdot\rangle\right) \tag{4.2}
\end{equation*}
$$

where $t, s$ are the Cartesian coordinates on $I \times \mathbb{R}$, we identify $d t, d s$ and $\langle\cdot, \cdot\rangle$ with their pullbacks to $\widehat{M}$, and the function $\kappa: \widehat{M} \rightarrow \mathbb{R}$ is defined by

$$
\kappa(t, s, v)=f(t)\langle v, v\rangle+\langle A v, v\rangle
$$

Thus, translations in the $s$ direction are isometries of $(\widehat{M}, \widehat{g})$.
It is well known [4, Theorem 4.1] that (4.2) is a rank-one ECS manifold. To describe its isometry group, we need two ingredients. The first is

$$
\begin{align*}
& \text { the subgroup } \mathrm{S} \text { of } \operatorname{Aff}(\mathbb{R}) \times \mathrm{O}(V) \text { formed by } \\
& \text { triples }(q, p, C) \text { such that } C A C^{-1}=q^{2} A \text {, while }  \tag{4.3}\\
& q t+p \in I \text { and } f(t)=q^{2} f(q t+p) \text { for all } t \in I,
\end{align*}
$$

$\mathrm{O}(V)$ being the group of linear $\langle\cdot, \cdot\rangle$-isometries $C: V \rightarrow V$.
The second ingredient is the $2(n-2)$-dimensional real
vector space $\mathcal{E}$ of all solutions $u: I \rightarrow V$ to the second-order ordinary
differential equation $\ddot{u}=f u+A u$, carrying the symplectic
form $\Omega: \mathcal{E} \times \mathcal{E} \rightarrow \mathbb{R}$ given by $\Omega\left(u^{+}, u^{-}\right)=\left\langle\dot{u}^{+}, u^{-}\right\rangle-\left\langle u^{+}, \dot{u}^{-}\right\rangle$.
Note that $q,(q, p), C$ all depend homomorphically on the triple $\sigma=(q, p, C)$, and S acts from the left on $C^{\infty}(I, V)$ via

$$
\begin{equation*}
[\sigma u](t)=C u((t-p) / q) \tag{4.5}
\end{equation*}
$$

while the operator $u \mapsto \sigma u$ leaves the solution space $\mathcal{E}$ invariant.

Theorem 4.1. For $(\widehat{M}, \widehat{g})$ and S as in (4.1)-(4.3), the full isometry group $\operatorname{Iso}(\widehat{M}, \widehat{g})$ is isomorphic to the set $\mathrm{G}=\mathrm{S} \times \mathbb{R} \times \mathcal{E} \subseteq \operatorname{Aff}(\mathbb{R}) \times \mathrm{O}(V) \times \mathbb{R} \times \mathcal{E}$ endowed with the group operation

$$
\begin{align*}
& (q, p, C, r, u)(\hat{q}, \hat{p}, \hat{C}, \hat{r}, \hat{u}) \\
& \quad=(q \hat{q}, q \hat{p}+p, C \hat{C},-\Omega(u,(q, p, C) \hat{u})+r+\hat{r} / q,(q, p, C) \hat{u}+u) \tag{4.6}
\end{align*}
$$

or, in the notation of (4.4)-(4.5), with $\sigma=(q, p, C)$,

$$
(\sigma, r, u)(\hat{\sigma}, \hat{r}, \hat{u})=(\sigma \hat{\sigma}, \Omega(\sigma \hat{u}, u)+r+\hat{r} / q, \sigma \hat{u}+u)
$$

The required isomorphism amounts to the following left action on $\widehat{M}$ by the group G with the operation (4.6):

$$
\begin{align*}
& (q, p, C, r, u)(t, s, v) \\
& \quad=(q t+p,-\langle\dot{u}(q t+p), 2 C v+u(q t+p)\rangle+r+s / q, C v+u(q t+p)) \tag{4.7}
\end{align*}
$$

Proof. This is precisely [1, Theorem 2], plus [1, p. 24, formula (22)] describing the group operation, except for the fact that [1] assumes real-analyticity of $f$ along with $I=\mathbb{R}$, and it is because of these assumptions that $|q|=1$ whenever $(q, p, C) \in \mathrm{S}$, cf. (4.3). If one ignores the last conclusion and the assumptions that led to it, the proof in [1] repeated almost verbatim in our case yields our assertion. However, the resulting right-hand side in (4.7) is not ours, but instead reads

$$
(q t+p,-\langle\dot{u}(t), 2 C v+u(t)\rangle+r+s / q, C v+u(t))
$$

due to the fact that $u$, instead of $\mathcal{E}$, now lies in the solution space $\mathcal{E}_{q}$ of the $q$-dependent equation $\ddot{u}=f u+q^{2} A u$. We reconcile both versions by observing that the replacement of $u$ with $t \mapsto u(q t+p)$ defines an isomorphism $\mathcal{E}_{q} \rightarrow \mathcal{E}$.

The notation of [1] differs from ours: our $q, p, C, r, u, t, s, v, V, f, \kappa, A,\langle\cdot, \cdot\rangle, \Omega$ correspond to $\varepsilon, T, H_{\mu}^{\lambda}, r, C^{\lambda}, x^{1}, 2 x^{n}, \mathbb{R}^{n-2}, A, \varphi, a_{\lambda \mu}, k_{\lambda \mu}, 2 \omega$ in [1].

By (4.6), $\mathrm{G} \ni \gamma=(\sigma, r, u) \mapsto \sigma \in \mathrm{S}$ is a group homomorphism, leading to

$$
\begin{equation*}
\text { the normal subgroup } \mathrm{H}=\{(1,0, \mathrm{Id})\} \times \mathbb{R} \times \mathcal{E} \text { of } \mathrm{G} \tag{4.8}
\end{equation*}
$$

The group operation (4.6) restricted to H becomes
(a) $(1,0, \operatorname{Id}, \hat{r}, \hat{u})(1,0, \operatorname{Id}, r, u)=(1,0, \operatorname{Id}, \Omega(u, \hat{u})+\hat{r}+r, \hat{u}+u)$, and the action (4.7) of H on $\widehat{M}$ is explicitly given by
(b) $(1,0, \operatorname{Id}, r, u)(t, s, v)=(t,-\langle\dot{u}(t), 2 v+u(t)\rangle+r+s, v+u(t))$.

Treating the vector space $\mathcal{E}$ as an Abelian group we get, from (a), an obvious
(c) group homomorphism $\mathrm{H} \ni(1,0, \mathrm{Id}, r, u) \mapsto u \in \mathcal{E}$.

Also, as stated in [7, formula (6.5)], with a suitable affine substitution,
(d) $t$ in (4.2) can always be made equal to $t$ chosen as in (3.1), so that, in view of (4.6)-(4.7),
(e) the homomorphism $\mathrm{G} \ni(q, p, C, r, u) \mapsto(q, p)$ coincides with (3.2a). Furthermore, according to [6, the lines following formula (3.6)], $\widehat{\nabla} t$ in (3.1) equals twice the coordinate vector field in the $s$ coordinate direction, and so
(f) the flow of $\widehat{\nabla} t$ on $\widehat{M}$ is given by $\mathbb{R} \ni r \mapsto(1,0, \mathrm{Id}, 2 r, 0) \in \mathrm{H} \subseteq \mathrm{G}$. In other words, cf. (b), the flow acts on $\widehat{M}$ via $(\tau,(t, s, v)) \mapsto(t, s+2 \tau, v)$. Also,
(g) $\sigma^{*} \Omega=q^{-1} \Omega$, as an obvious consequence of (4.4)-(4.5).

The subgroup H (canonically identified with $\mathbb{R} \times \mathcal{E}$ ) acts both on the product $I \times \mathbb{R} \times \mathcal{E}$, by left H-translations of the $\mathrm{H} \approx \mathbb{R} \times \mathcal{E}$ factor, and on $\widehat{M}$, via (b). The following mapping is H -equivariant for these two actions:

$$
\begin{equation*}
I \times \mathbb{R} \times \mathcal{E} \ni(t, z, u) \mapsto(t, s, v)=(t, z-\langle\dot{u}(t), u(t)\rangle, u(t)) \in \widehat{M}=I \times \mathbb{R} \times V \tag{4.9}
\end{equation*}
$$

as one easily verifies using (a), (b) and the definition of $\Omega$ in (4.4).
Remark 4.2. It is useful to note that $(\sigma, r, u)^{-1}=\left(\sigma^{-1},-q r,-\sigma^{-1} u\right)$ in G , which yields, for $(\sigma, \hat{r}, \hat{u})=(q, p, C, \hat{r}, \hat{u}) \in \mathrm{G}$ and $(1,0, \mathrm{Id}, r, u) \in \mathrm{H}$, the equality

$$
(\sigma, \hat{r}, \hat{u})(1,0, \operatorname{Id}, r, u)(\sigma, \hat{r}, \hat{u})^{-1}=(1,0, \operatorname{Id}, 2 \Omega(\sigma u, \hat{u})+r / q, \sigma u)
$$

Remark 4.3. Nondegeneracy of $\Omega$ gives $\operatorname{dim} \mathscr{L}^{\prime}=\operatorname{dim} \mathscr{E}-\operatorname{dim} \mathscr{L}$ for any vector subspace $\mathscr{L} \subset \mathcal{E}$ and its $\Omega$-orthogonal complement $\mathscr{L}^{\prime}$. Thus, $2 \operatorname{dim} \mathscr{L} \leq \operatorname{dim} \mathcal{E}$ whenever $\mathscr{L}$ is isotropic in the sense that $\Omega\left(u, u^{\prime}\right)=0$ for all $u, u^{\prime} \in \mathscr{L}$.

Remark 4.4. We refer to a rank-one ECS model manifold (4.2) as generic when so is $A$ in (4.1), by which we mean that $A$ commutes with only finitely many linear $\langle\cdot, \cdot\rangle$-isometries of $V$. Genericity of $A$ in (4.1) is an intrinsic property of the metric $\widehat{g}$, rather than just a condition imposed on the construction (4.1)-(4.2): as stated in [7, the paragraph following formula (7.3)], the algebraic type of the pair $\langle\cdot, \cdot\rangle, A$, up to rescaling of $A$, can be explicitly defined in terms of $\hat{g}$ and its Weyl tensor.

Remark 4.5. The relation $C A C^{-1}=q^{2} A$ in (4.3) with $|q| \neq 1$ implies nilpotency of $A$, as all complex characteristic roots of $A$ then obviously equal 0 .

## 5. Generic self-adjoint nilpotent endomorphisms

Throughout this section, $V$ denotes a real vector space of dimension $m \geq 2$.
Given a pseudo-Euclidean inner product $\langle\cdot, \cdot\rangle$ on $V$, we refer to $\langle\cdot, \cdot\rangle$ as semineutral if its positive and negative indices differ by at most one, and - following the
terminology of Remark 4.4 - call a $\langle\cdot, \cdot \cdot\rangle$-self-adjoint endomorphism of $V$ generic when it commutes with only a finite number of linear $\langle\cdot, \cdot\rangle$-isometries of $V$. As we show below (Remark 5.4), for $\langle\cdot, \cdot\rangle$-self-adjoint endomorphisms $A$ of $V$ which are nilpotent, genericity is equivalent to having $A^{m-1} \neq 0$ (while $A^{m}=0$ ).

Nilpotent endomorphisms are relevant to our discussion due to Remark 4.5. Generally, for any endomorphism $A$ of our vector space $V$ and any integer $j \geq 1$, the inclusions $\operatorname{Ker} A^{j-1} \subseteq \operatorname{Ker} A^{j}$ lead to the quotient spaces $\operatorname{Ker} A^{j} / \operatorname{Ker} A^{j-1}$, and then $A$ obviously descends to injective linear operators

$$
\begin{equation*}
A: \operatorname{Ker} A^{j+1} / \operatorname{Ker} A^{j} \rightarrow \operatorname{Ker} A^{j} / \operatorname{Ker} A^{j-1}, \quad j=1, \ldots, m-1 \tag{5.1}
\end{equation*}
$$

Setting $d_{j}=\operatorname{dim}\left[\operatorname{Ker} A^{j} / \operatorname{Ker} A^{j-1}\right]$ we thus have $d_{j} \geq d_{j+1}$ and, if $A$ is nilpotent,

$$
\begin{equation*}
d_{1} \geq \cdots \geq d_{m} \geq 0 \quad \text { and } \quad \operatorname{dim} V=d_{1}+\cdots+d_{m} \tag{5.2}
\end{equation*}
$$

while, whenever $j=0, \ldots, m$,

$$
\begin{equation*}
\operatorname{dim} \operatorname{Ker} A^{j}=d_{1}+\cdots+d_{j}, \quad \operatorname{rank} A^{j}=d_{j+1}+\cdots+d_{m} \tag{5.3}
\end{equation*}
$$

Thus, $d_{m} \geq 1$ in the case where $A$ is nilpotent and $A^{m-1} \neq 0$, and then, by (5.2),

$$
\begin{equation*}
d_{1}=\cdots=d_{m}=1 \text { and (5.1) is an isomorphism for } j=1, \ldots, m-1 \tag{5.4}
\end{equation*}
$$

Theorem 5.1. Let a $\langle\cdot, \cdot\rangle$-self-adjoint nilpotent endomorphism $A$ of an m-dimensional pseudo-Euclidean vector space $V$ have $A^{m-1} \neq 0$. Then the inner product $\langle\cdot, \cdot\rangle$ is sem-$i$-neutral and there exist exactly two bases $e_{1}, \ldots, e_{m}$ of $V$, differing by an overall sign change, as well as a unique sign factor $\varepsilon= \pm 1$, such that $A e_{j}=e_{j-1}$ and $\left\langle e_{i}, e_{k}\right\rangle=$ $\varepsilon \delta_{i j}$ for all $i, j \in\{1, \ldots, m\}$, where $e_{0}=0$ and $k=m+1-j$. Equivalently, the matrix representing $A$ or, respectively, $\langle\cdot, \cdot\rangle$ in our basis has zero entries except those immediately above the main diagonal, all equal to 1 or, respectively, except those on the main antidiagonal, all equal to $\varepsilon$.

Conversely, if $A$ and $\langle\cdot, \cdot\rangle$ are of the above form in some basis $e_{1}, \ldots, e_{m}$ of $V$, then $A$ is $\langle\cdot, \cdot\rangle$-self-adjoint, nilpotent and $A^{m-1} \neq 0$.

Proof. For $j=0, \ldots, m$, the symmetric bilinear form $\left(v, v^{\prime}\right) \mapsto\left\langle A^{j} v, v^{\prime}\right\rangle$ on $V$, briefly denoted by $\left\langle A^{j} \cdot, \cdot\right\rangle$, and the subspaces $V_{j}=A^{j}(V) \subseteq V$, we have
(a) $\operatorname{dim} V_{j}=m-j$ and $V_{j} \subseteq V_{j-1}$ if $j \geq 1$,
(b) $\left\langle A^{m-j} \cdot, \cdot\right\rangle$ descends to the $j$-dimensional quotient space $V / V_{j}$, with (a) being obvious from (5.3)-(5.4), and (b) from
(c) self-adjointness of $A$ along with the relation $A^{m}=0$.

As $A^{m-1} \neq 0$, the form resulting from (b) on the line $V / V_{1}$ is nonzero, and hence positive or negative definite, which proves the existence and uniqueness of a sign
factor $\varepsilon \in\{1,-1\}$ such that $\left\langle A^{m-1} v, v\right\rangle=\varepsilon$ for some $v \in V$. More precisely, $\varepsilon$ is the semidefiniteness sign of $\left\langle A^{m-1} \cdot, \cdot\right\rangle$, and
(d) vectors with $\left\langle A^{m-1} v, v\right\rangle=\varepsilon$ form a pair of opposite cosets of $V_{1}$ in $V$.

We now prove, by induction on $j=1, \ldots, m$, the existence of an ordered $j$-tuple $\left(S_{1}, \ldots, S_{j}\right) \in V / V_{1} \times \cdots \times V / V_{j}$ of cosets such that $S_{j} \subseteq \cdots \subseteq S_{1}$ while, for $\varepsilon$ in (d) and every $v \in S_{j}$,

$$
\begin{equation*}
\left\langle A^{m-1} v, v\right\rangle=\varepsilon, \quad\left\langle A^{m-2} v, v\right\rangle=\cdots=\left\langle A^{m-j} v, v\right\rangle=0 \tag{5.5}
\end{equation*}
$$

along with uniqueness of $\left(S_{1}, \ldots, S_{j}\right)$ up to its replacement by $\left(-S_{1}, \ldots,-S_{j}\right)$. As (d) yields our claim for $j=1$, suppose that it holds for some $j-1 \geq 1$. Since $V_{j} \subseteq$ $V_{j-1} \subseteq \cdots \subseteq V_{1}$, cf. (a),
(e) the spaces $V_{j-1}, \ldots, V_{1}$ project onto subspaces $Q_{1}, \ldots, Q_{j-1}$ of dimensions $1, \ldots, j-1$ in the $j$-dimensional quotient $Q_{j}=V / V_{j}$,
and $Q_{1} \subseteq \cdots \subseteq Q_{j-1}$, while the cosets $S_{j-1}, \ldots, S_{1}$ of $V_{j-1}, \ldots, V_{1}$ in $V$, assumed to exist (and be unique up to an overall sign), project onto an ascending chain of cosets of $Q_{1}, \ldots, Q_{j-1}$ in $Q_{j}$. Let us fix a vector $v \in S_{j-1}$, denote by $\widehat{R}_{1}, \ldots, \widehat{R}_{j-1}$ the latter cosets (of dimensions $1, \ldots, j-1$ ), and by $(\cdot, \cdot)$ the symmetric bilinear form on $Q_{j}$ induced by $\left\langle A^{m-j} \cdot, \cdot\right\rangle$ via (b). Since (5.5) is assumed to hold for our $v$, with $j$ replaced by $j-1$, if we set $v_{i}=A^{j-i} v, i=1, \ldots, j$, then, for all $i, k \in$ $\{1, \ldots, j\}$, due to (c) and the first equality in this version of (5.5), $\left(v_{i}, v_{k}\right)=0$ if $i+k \leq j$ and $\left(v_{i}, v_{k}\right)=\varepsilon$ when $i+k=j+1$. The $j \times j$ matrix of these $(\cdot, \cdot)-$ inner products thus has the entries all equal to $\varepsilon$ on the main antidiagonal, and all zero above it. Due to the resulting nondegeneracy of the matrix and the presence of the zero entries, $v_{1}, \ldots, v_{j}$ project onto a basis $\widehat{v}_{1}, \ldots, \hat{v}_{j}$ of $Q_{j}$, with $\hat{v}_{i} \in Q_{i}$, $i=1, \ldots, j$, and $(\cdot, \cdot)$ is a semi-neutral pseudo-Euclidean inner product in $Q_{j}$. Thus, $\widehat{v}_{1} \in Q_{1}$ is $(\cdot, \cdot)$-orthogonal to the basis $\hat{v}_{1}, \ldots, \hat{v}_{j-1}$ of $Q_{j-1}$, which makes $Q_{j-1}$ the $(\cdot, \cdot)$-orthogonal complement of the $(\cdot, \cdot)$-null line $Q_{1}$. At the same time, the coset $\widehat{R}_{1}$ of $Q_{1}$ is not contained in the $(\cdot, \cdot)$-orthogonal complement $Q_{j-1}$ of $Q_{1}$, since $\left(v_{1}, v\right)=\left(A^{j-1} v, v\right)=\left\langle A^{m-1} v, v\right\rangle=\varepsilon \neq 0$ in the $j-1$ version of (5.5), and so the vector $v=v_{j} \in S_{j-1}$, projecting onto $\widehat{v}_{j} \in \widehat{R}_{1}$, is not $(\cdot, \cdot)$-orthogonal to $\widehat{v}_{1}$ spanning the line $Q_{1}$. By Lemma 2.1, $\widehat{R}_{1}$ intersects the $(\cdot, \cdot)$-null cone at exactly one point, and so does $-\widehat{R}_{1}$. This "point" in the $j$-dimensional quotient $Q_{j}=V / V_{j}$ is actually a coset $S_{j}$ of $V_{j}$ in $V$, contained in $S_{j-1}$, and its lying in the $(\cdot, \cdot)$-null cone amounts to $\left\langle A^{m-j} v, v\right\rangle=0$ for all $v \in S_{j}$, which establishes the inductive step and thus proves the existence and uniqueness claim about (5.5).

This last claim, for $j=m$, yields a unique (up to a sign) coset $S_{m}$ of $V_{m}=\{0\}$, that is, a unique pair $\{v,-v\}$ of opposite vectors in $V$, with

$$
\begin{equation*}
\left\langle A^{m-1} v, v\right\rangle=\varepsilon \quad \text { and } \quad\left\langle A^{i} v, v\right\rangle=0 \quad \text { whenever } i \geq 0 \text { and } i \neq m-1 \tag{5.6}
\end{equation*}
$$

the case of $i<m-1$ being due to (5.5) for $j=m$, that of $i \geq m$ immediate from (c). Note that $S_{m}$ uniquely determines the other cosets $S_{j}$ as $S_{m} \subseteq \cdots \subseteq S_{1}$. Setting $e_{i}=A^{m-i} v, i=1, \ldots, m$, we obtain an $m$-tuple of vectors leading to matrices for $A$ and $\langle\cdot, \cdot\rangle$ described in the statement of the theorem, cf. (c) and (5.6). Nondegeneracy of the latter matrix, along with the abundance of zero entries in it, establishes both linear independence of $e_{1}, \ldots, e_{m}$ and the semi-neutral signature of $\langle\cdot, \cdot\rangle$. Uniqueness of $\{v,-v\}$ clearly implies uniqueness of $e_{1}, \ldots, e_{m}$ up to their replacement by $-e_{1}, \ldots,-e_{m}$.

For the converse statement it suffices to note that the basis $e_{1}, \ldots, e_{m}$ has the form $A^{m-1} v, A^{m-2} v, \ldots, A v, v$, and so self-adjointness of $A$ amounts to requiring that the matrix of $\langle\cdot, \cdot\rangle$ has a single value of the entries in each antidiagonal.

Corollary 5.2. The only linear isometries of a pseudo-Euclidean space of dimension $m$ commuting with a given generic nilpotent self-adjoint endomorphism $A$ such that $A^{m-1} \neq 0$ are Id and -Id.

In fact, due to the up-to-a-sign uniqueness of the basis in Theorem 5.1, such a linear isometry must transform this basis into itself or its opposite.

Corollary 5.3. Let a nilpotent self-adjoint endomorphism A of a pseudo-Euclidean space $V$ have $A^{m-1} \neq 0$, where $m=\operatorname{dim} V$. Then, for every $q \in(0, \infty)$, there exists a unique pair $\{C,-C\}$ of mutually opposite linear isometries of $V$ with $C A C^{-1}=q^{2} A$.

Such $C$ is diagonalized by a basis $e_{1}, \ldots, e_{m}$ chosen as in Theorem 5.1, with the respective eigenvalues $q^{m-1}, q^{m-3}, \ldots, q^{1-m}$, or their opposites, so that $C e_{j}=$ $\pm q^{m+1-2 j} e_{j}$ for $j=1, \ldots, m$ and some fixed sign $\pm$.

Proof. Uniqueness is immediate from Corollary 5.2 since two such linear isometries differ, composition-wise, by one commuting with $A$. Existence: defining the linear automorphism $C$ by $C e_{j}=\tilde{e}_{j}$, for $\tilde{e}_{j}=q^{m+1-2 j} e_{j}$, we get the inner products $\left\langle\tilde{e}_{i}, \tilde{e}_{k}\right\rangle=\varepsilon \delta_{i j}$, and $q^{2} A \tilde{e}_{j}=\tilde{e}_{j-1}$, for all $i, j \in\{1, \ldots, m\}$, with $k=m+1-j$ and $\tilde{e}_{0}=0$, as required.

Remark 5.4. For a nilpotent self-adjoint endomorphism $A$ of an $m$-dimensional pseudo-Euclidean space $V$, five conditions are mutually equivalent:
(i) $A^{m-1} \neq 0$.
(ii) $\operatorname{rank} A=m-1$ (in other words, $\operatorname{dim} \operatorname{Ker} A=1$ ).
(iii) $\pm \mathrm{Id}$ are the only linear self-isometries of $V$ commuting with $A$.
(iv) $A$ is generic (commutes with only finitely many linear isometries).
(v) 0 is the only skew-adjoint endomorphism of $V$ commuting with $A$.

In fact, (i) yields (ii) due to (5.3)-(5.4), and the converse is immediate as (ii) and (5.2)(5.3) force all $d_{j}$ to equal 1 . The implications (i) $\Longrightarrow$ (iii) $\Longrightarrow$ (iv) $\Longrightarrow$ (v) are obvious from Corollary 5.2. Finally, (v) implies (ii) as any two vectors $v, v^{\prime} \in \operatorname{Ker} A$ are linearly dependent: the skew-adjoint endomorphism $v \wedge v^{\prime}=\langle v, \cdot\rangle v^{\prime}-\left\langle v^{\prime}, \cdot\right\rangle v$, where $\langle\cdot, \cdot\rangle$ is the inner product, commutes with $A$.

## 6. Invariant subspaces

This section uses the following assumptions and notations.
First, we fix $q \in(0, \infty) \backslash\{1\}$, an integer $m \geq 2$, a generic self-adjoint nilpotent endomorphism $A$ of an $m$-dimensional pseudo-Euclidean space $V$ with the inner product $\langle\cdot, \cdot\rangle$, and a linear $\langle\cdot, \cdot\rangle$-isometry $C$ of $V$ having positive eigenvalues and satisfying the condition $C A C^{-1}=q^{2} A$.

According to Remark 5.4, Theorem 5.1 and Corollary 5.3, the algebraic type of the above quadruple $(V,\langle\cdot, \cdot\rangle, A, C)$ is uniquely determined by $m, q$ and a sign parameter $\varepsilon= \pm 1$. More precisely, we may choose a basis $e_{1}, \ldots, e_{m}$ of $V$ such that, for some $\varepsilon \in\{1,-1\}$ and all $i, j \in\{1, \ldots, m\}$, with $e_{0}=0$ and $k=m+1-j$,

$$
\begin{equation*}
A e_{j}=e_{j-1}, \quad\left\langle e_{i}, e_{k}\right\rangle=\varepsilon \delta_{i j}, \quad C e_{j}=q^{m+1-2 j} e_{j} \tag{6.1}
\end{equation*}
$$

Let the operator $T$ act on functions $(0, \infty) \ni t \mapsto u(t)$, valued anywhere, by

$$
\begin{equation*}
[T u](t)=u(t / q) \tag{6.2}
\end{equation*}
$$

We also fix a $C^{\infty}$ function

$$
\begin{equation*}
f:(0, \infty) \rightarrow \mathbb{R} \quad \text { with } q^{2} f(q t)=f(t) \text { whenever } t \in(0, \infty) \tag{6.3}
\end{equation*}
$$

and define $\mathcal{W}, \mathcal{E}$ to be the vector spaces of dimensions 2 and $2 m$ formed by all realvalued (or, $V$-valued) functions $y$ (or, $u$ ) on $(0, \infty)$ such that

$$
\begin{equation*}
\ddot{y}=f y \tag{6.4-i}
\end{equation*}
$$

or, respectively,

$$
\begin{equation*}
\ddot{u}=f u+q^{2} A u \tag{6.4-ii}
\end{equation*}
$$

with ( $)^{\cdot}=d / d t$. The operator $T$ obviously preserves $\mathcal{W}$, and so we may select a basis $y^{+}, y^{-}$of the space of complex-valued solutions to (6.4-i) having

$$
\begin{equation*}
T y^{+}=\mu^{+} y^{+} \text {and } T y^{-} \text {equal to } \mu^{-} y^{-} \text {plus a multiple of } y^{+} \tag{6.5}
\end{equation*}
$$

for some eigenvalues $\mu^{ \pm} \in \mathbb{C}$, the multiple being zero unless $\mu^{+}=\mu^{-} \in \mathbb{R}$. Since the formula $\alpha\left(y^{+}, y^{-}\right)=\dot{y}^{+} y^{-}-y^{+} \dot{y}^{-}$(a constant!) defines an area form on $\mathcal{W}$ such that $T^{*} \alpha=q^{-1} \alpha$, we have $\operatorname{det} T=q^{-1}$ in $\mathcal{W}$. Consequently,

$$
\begin{equation*}
\mu^{+} \mu^{-}=q^{-1} \tag{6.6}
\end{equation*}
$$

In general, $\mathcal{E}$ is not preserved by either $T$ or by $C$ applied valuewise via $u \mapsto C u$. Their composition $C T=T C$ however, does leave $\mathcal{E}$ invariant,

$$
\begin{equation*}
C T: \mathcal{E} \rightarrow \mathcal{E} \tag{6.7}
\end{equation*}
$$

as it coincides with the operator $u \mapsto \sigma u$ in (4.5). The solution space $\mathcal{E}$ of (6.4-ii) has an ascending $m$-tuple of $C T$-invariant vector subspaces

$$
\begin{equation*}
\mathcal{E}_{1} \subseteq \cdots \subseteq \mathcal{E}_{m}=\mathcal{E} \quad \text { with } \operatorname{dim} \varepsilon_{j}=2 j \tag{6.8}
\end{equation*}
$$

each $\mathcal{E}_{j}$ consisting of solutions taking values in the space $\operatorname{Ker} A^{j}$. (Note that, as a consequence of (5.3)-(5.4), $\operatorname{dim} \operatorname{Ker} A^{j}=j$.)
Theorem 6.1. Given $q, m, V,\langle\cdot, \cdot\rangle, A, C, e_{1}, \ldots, e_{m}, T, f, \mathcal{W}, \mathcal{E}, y^{ \pm}, \mu^{ \pm}$introduced earlier in this section, let $\mathscr{L}$ be any $C T$-invariant subspace of $\mathcal{E}$. Then in some basis $u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}$of the complexification $\mathcal{E}^{\mathbb{C}}$ of $\mathcal{E}$, containing a basis of $\mathscr{L}^{\mathbb{C}}$, the matrix of $C T$ is upper triangular with the diagonal $\left(\lambda_{1}^{+}, \lambda_{1}^{-}, \ldots, \lambda_{m}^{+}, \lambda_{m}^{-}\right)$where, for some combination coefficients $(0, \infty) \rightarrow \mathbb{C}$,

$$
\begin{equation*}
\lambda_{j}^{ \pm}=q^{m+1-2 j} \mu^{ \pm} \text {and } u_{j}^{ \pm} \text {equals } y^{ \pm} e_{j} \text { plus a combination of } e_{1}, \ldots, e_{j-1} \tag{6.9}
\end{equation*}
$$

$j=1, \ldots$, m. If $\mu^{+}, \mu^{-} \in \mathbb{R}$, we may replace "complex-valued" by "real-valued" and the complexifications $\mathbb{C}, \varepsilon^{\mathbb{C}}, \varepsilon_{j}^{\mathbb{C}}$ by the original real forms $\mathbb{R}, \mathcal{E}, \mathcal{E}_{j}$.
Proof. The equation $\ddot{u}=f u+A u$ imposed on $u=y_{1} e_{1}+\cdots+y_{j} e_{j}$, with $1 \leq j \leq$ $m$ and complex-valued functions $y_{1}, \ldots, y_{j}$, reads

$$
\begin{equation*}
\ddot{y}_{j}=f y_{j} \quad \text { and } \quad \ddot{y}_{i}=f y_{i}+y_{i+1} \quad \text { for } i<j . \tag{6.10}
\end{equation*}
$$

Since, by (6.1), $e_{1}, \ldots, e_{j}$ span $\operatorname{Ker} A^{j}$, such $u$ lies in $\mathcal{E}_{j}^{\mathbb{C}}$, for $\mathcal{E}_{j}$ appearing in (6.8), and we can now define $u_{j}^{ \pm}$by (6.9), declaring $y_{j}$ in (6.10) to be $y^{ \pm}$and then solving the equations $\ddot{y}_{i}=f y_{i}+y_{i+1}$ in the descending order $i=j-1, \ldots, 1$, with a $2(j-1)$-dimensional freedom of choosing the functions $y_{i}$. As $u_{j}^{ \pm} \notin \mathcal{E}_{i}^{\mathrm{C}}$ for $i<j$, the $2 m$ solutions $u_{j}^{ \pm}$are linearly independent, and hence constitute a basis $u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}$of $\mathcal{E}^{\mathbb{C}}$ which makes $C T$ upper triangular with the required diagonal. More precisely, by (6.1)-(6.5), $C T u_{j}^{+}$(or, $C T u_{j}^{-}$) equals $q^{m+1-2 j} \mu^{+} u_{j}^{+}$(or, $q^{m+1-2 j} \mu^{-} u_{j}^{-}$plus a multiple of $u_{j}^{+}$), plus a linear combination of $u_{i}^{ \pm}$with $i<j$, the multiple being 0 unless $\mu^{+}=\mu^{-} \in \mathbb{R}$.

The freedom of choosing $y_{i}$ will now ensure that some $u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}$as above also contains a basis of $\mathscr{L}^{\mathbb{C}}$. Namely, for $\mathscr{L}_{j}=\mathscr{L} \cap \mathcal{E}_{j}$, we get inclusioninduced, obviously injective operators $\mathscr{L}_{j} / \mathscr{L}_{j-1} \rightarrow \mathcal{E}_{j} / \mathcal{E}_{j-1}$, where $1 \leq j \leq m$ and $\mathscr{L}_{0}=\mathcal{E}_{0}=\{0\}$, so that, by (6.8), $\delta_{j} \in\{0,1,2\}$, with $\delta_{j}=\operatorname{dim}\left(\mathscr{L}_{j} / \mathscr{L}_{j-1}\right)$. Our $u_{j}^{ \pm}$may now be left completely arbitrary, as before, when $\delta_{j}=0$. If $j$ is fixed and $\delta_{j}=2$, our operator $\mathscr{L}_{j} / \mathscr{L}_{j-1} \rightarrow \mathcal{E}_{j} / \mathcal{E}_{j-1}$ is an isomorphism, and so the cosets of $u_{j}^{ \pm}$, forming a basis of $\left[\mathcal{E}_{j} / \mathcal{E}_{j-1}\right]^{\mathbb{C}}$, are also realized as $\mathscr{L}_{j-1}^{\mathbb{C}}$ cosets of solutions in $\mathscr{L}_{j}^{\mathbb{C}}$, which we select as the required modified versions of $u_{j}^{ \pm}$. Finally, in the case $\delta_{j}=1$, the embedded line $\left[\mathscr{L}_{j} / \mathscr{L}_{j-1}\right]^{\mathbb{C}}$ in $\left[\mathcal{E}_{j} / \mathcal{E}_{j-1}\right]^{\mathbb{C}}$, due to its $C T$-invariance, must be one of the two eigenvector cosets represented by $u_{j}^{ \pm}$, and the latter can thus be modified (within our $2(j-1)$-dimensional freedom) so as to lie in $\mathscr{L}_{j}^{\mathbb{C}}$. Since $\delta_{j}=\operatorname{dim}\left(\mathscr{L}_{j} / \mathscr{L}_{j-1}\right)$, the total number of modified solutions, $\delta_{1}+\cdots+\delta_{m}$, equals $\operatorname{dim} \mathscr{L}$. Therefore, they form a basis of $\mathscr{L}^{\mathbb{C}}$.

## 7. GL(Z)-polynomials

By a root of unity, or a $\mathrm{GL}(\mathbb{Z})$-polynomial we mean here any complex number $z$ such that $z^{k}=1$ for some integer $k \geq 1$ or, respectively, any polynomial of degree $d \geq 1$ with integer coefficients, the leading coefficient $(-1)^{d}$, and the constant term 1 or -1 . It is well known, cf. [5, p. 75], that
$\mathrm{GL}(\mathbb{Z})$-polynomials of degree $d$ are precisely the characteristic polynomials of matrices in $\operatorname{GL}(d, \mathbb{Z})$.

Every complex root $a$ of a GL( $\mathbb{Z})$-polynomial $P$ is an invertible algebraic integer and $P$, if also assumed irreducible, is the minimal monic polynomial of $a$. Then, due to minimality, $a$ is not a root of the derivative of $P$, showing that
the complex roots of an irreducible $G L(\mathbb{Z})$-polynomial are all distinct.
Irreducibility is always meant here to be over $\mathbb{Z}$ or, equivalently, over $\mathbb{Q}$.
We say that a $\mathrm{GL}(\mathbb{Z})$-polynomial has a cyclic root group if its (obviously nonzero) complex roots generate a cyclic multiplicative group of nonzero complex numbers. The goal of this section is to show that
the only irreducible $\mathrm{GL}(\mathbb{Z})$-polynomials with a cyclic root group are the cyclotomic and quadratic ones.

We call an irreducible $\mathrm{GL}(\mathbb{Z})$-polynomial cyclotomic if all of its roots are roots of unity which, up to a sign, agrees with the standard terminology [11]. The cyclic rootgroup condition clearly does hold for all cyclotomic polynomials and all quadratic $\mathrm{GL}(\mathbb{Z})$-polynomials.

First, if an irreducible GL( $\mathbb{Z}$ )-polynomial $P$ has among its roots $a$ and $a^{k}$, for some $a \in \mathbb{C} \backslash\{1,-1\}$ and an integer $k \notin\{0,1,-1\}$, then

$$
\begin{equation*}
\text { every complex root of } P \text { is a root of unity. } \tag{7.4}
\end{equation*}
$$

In fact, if $k \geq 2$, then, for such $P, a$, all $\lambda \in \mathbb{C}$, all integers $r \geq 1$, and some $\mathrm{GL}(\mathbb{Z})$ polynomial $Q$,

$$
\begin{equation*}
P\left(\lambda^{k^{r}}\right)=Q(\lambda) Q\left(\lambda^{k}\right) \cdots Q\left(\lambda^{k^{r-1}}\right) P(\lambda) \tag{7.5}
\end{equation*}
$$

as one sees using induction on $r$, the case $r=1$ being obvious as $\lambda \mapsto P\left(\lambda^{k}\right)$ has $a$ as a root, which makes it divisible by the minimal polynomial $P$ of $a$, and the induction step amounts to replacing $\lambda$ in (7.5) by $\lambda^{k}$. Now (7.4) follows, or else $P$ would have infinitely many roots. The extension of (7.4) to negative integers $k$ is in turn immediate if one notes that $(P Q)^{*}=P^{*} Q^{*}$ and $P^{* *}=P$ for the inversion $P^{*}$ of a degree $d$ polynomial $P$, defined by $P^{*}(\lambda)=\lambda^{d} P(1 / \lambda)$ or, equivalently, $P^{*}(\lambda)=a_{0} \lambda^{d}+\cdots+a_{d-1} \lambda+a_{d}$ whenever $P(\lambda)=a_{0}+a_{1} \lambda+\cdots+a_{d} \lambda^{d}$. More precisely, we then replace (7.5) with $P\left(\lambda^{k^{r}}\right)=Q^{*}(\lambda) Q\left(\lambda^{k}\right) \cdots Q^{[r]}\left(\lambda^{k^{r-1}}\right) P^{[r]}(\lambda)$, where $P^{[r]}$ equals $P$ or $P^{*}$ depending on whether $r$ is even or odd.

Remark 7.1. If a GL( $\mathbb{Z})$-polynomial has the complex roots $c_{1}, \ldots, c_{d}$, and $k$ is an integer, then $c_{1}^{k}, \ldots, c_{d}^{k}$ are the roots of a $\operatorname{GL}(\mathbb{Z})$-polynomial. (By (7.1), we may choose the latter polynomial to be the characteristic polynomial of the $k$ th power of a matrix in $\operatorname{GL}(d, \mathbb{Z})$ with the characteristic roots $c_{1}, \ldots, c_{d}$.)

Lemma 7.2. Let an irreducible $\mathrm{GL}(\mathbb{Z})$-polynomial $P$ of degree $d$ have a root $a^{k}$ for some $a \in \mathbb{C} \backslash\{1,-1\}$ and an integer $k \neq 0$. Then
a is an invertible algebraic integer,
having some $\mathrm{GL}(\mathbb{Z})$-polynomial $S$ as its minimal polynomial, and the complex roots $c_{1}, \ldots, c_{r}$ of $S$ can be rearranged so that, with $d \leq r$,

$$
\begin{equation*}
P(\lambda)=\left(c_{1}^{k}-\lambda\right) \cdots\left(c_{d}^{k}-\lambda\right) \quad \text { and } \quad\left\{c_{1}^{k}, \ldots, c_{d}^{k}\right\}=\left\{c_{1}^{k}, \ldots, c_{r}^{k}\right\} \tag{7.7}
\end{equation*}
$$

Proof. If $k>0$, the polynomial $\lambda \mapsto P\left(\lambda^{k}\right)$ has the root $a$, which yields (7.6) and the equality $P\left(\lambda^{k}\right)=Q(\lambda) S(\lambda)$ for all $\lambda \in \mathbb{C}$ and some $\operatorname{GL}(\mathbb{Z})$-polynomial $Q$. Thus, the $k$ th powers of all the roots $c_{1}, \ldots, c_{r}$ of $S$ are roots of $P$. The polynomial $R$ with the roots $c_{1}^{k}, \ldots, c_{r}^{k}$ is a GL( $\mathbb{Z}$ )-polynomial (Remark 7.1), while each factor in its unique irreducible factorization has simple roots by (7.2), which are also roots of $P$, and irreducibility of $P$ thus implies that the factor must equal $P$. In other words, $R$ is a power of $P$, and (7.7) follows. When $k<0$, the preceding assumptions (and conclusions) hold with $k, P$ replaced by $|k|, P^{*}$ (and $a, S$ unchanged), so that $P^{*}(\lambda)=\left(c_{1}^{|k|}-\lambda\right) \cdots\left(c_{d}^{|k|}-\lambda\right)$, as required in (7.7).

Lemma 7.3. If an irreducible $\mathrm{GL}(\mathbb{Z})$-polynomial $P$ has two roots of the form $a^{k}$ and $a^{\ell}$ for $a \in \mathbb{C} \backslash\{1,0,-1\}$ and two distinct nonzero integers $k, \ell \geq 2$, then all roots of $P$ have modulus 1 .

Proof. Let $k>\ell$. The two versions of (7.7), one for $k$ and one for $\ell$, involve the same roots $c_{1}, \ldots, c_{r}$ of the same polynomial $S$, so that

$$
\begin{equation*}
\left\{\left|c_{1}\right|^{k}, \ldots,\left|c_{r}\right|^{k}\right\}=\left\{\left|c_{1}\right|^{\ell}, \ldots,\left|c_{r}\right|^{\ell}\right\} \tag{7.8}
\end{equation*}
$$

If the greatest (or, least) of the moduli $\left|c_{1}\right|, \ldots,\left|c_{r}\right|$ were greater (or, less) than 1 , its $k$ th (or, $\ell$ th) power would lie on the left-hand (or, right-hand) side of (7.8) and be greater than any number on the opposite side, contrary to the equality in (7.8). Thus, $\left|c_{1}\right|=\cdots=\left|c_{r}\right|=1$.

Lemma 7.4. If all roots of an irreducible $\mathrm{GL}(\mathbb{Z})$-polynomial $P$ have modulus 1 , then they are roots of unity, that is, $P$ is cyclotomic.

Proof. A matrix in $\mathrm{GL}(d, \mathbb{Z})$ with the characteristic polynomial $P$, cf. (7.1), treated as an automorphism of $\mathbb{C}^{d}$ is, in view of (7.2), diagonalized by a suitable basis, with unit diagonal entries, so that its powers form a bounded sequence, with a convergent subsequence. As these powers preserve the real form $\mathbb{R}^{d} \subseteq \mathbb{C}^{d}$, the convergence takes place in $\operatorname{GL}(d, \mathbb{R})$ and discreteness of the subset $\operatorname{GL}(d, \mathbb{Z})$ makes the subsequence ultimately constant.

Proof of (7.3). Consider an irreducible $\mathrm{GL}(\mathbb{Z})$-polynomial with a cyclic root group generated by $a \in \mathbb{C}$. By (7.2), we may assume that $a \notin\{1,0,-1\}$. If $a$ is (or is not) a root, our claim follows from (7.4) (or, Lemmas 7.3-7.4).

## 8. The combinatorial argument

The main result of this section, Theorem 8.1, will serve as the final step needed to prove Theorem A in Section 9.

Any $m, k \in \mathbb{Z}$ with $m \geq 2$ give rise to functions $E, \Phi: \mathbb{Z} \rightarrow \mathbb{Z}$ and integers $a_{0}, a_{1}$ such that, for all $a, b \in \mathbb{Z}$,

$$
\begin{align*}
& E(a)=m-(-1)^{a} k-a  \tag{8.1-i}\\
& \Phi(a)=2 m-2(-1)^{a} k-a \tag{8.1-ii}
\end{align*}
$$

$$
\begin{align*}
E^{-1}(b) & =m-(-1)^{m+k+b} k-b  \tag{8.1-iv}\\
\Phi(a) & =E^{-1}(-E(a))  \tag{8.1-v}\\
a_{1} & =E^{-1}(1)=m+(-1)^{m+k} k-1
\end{align*}
$$

$$
\begin{align*}
a_{0} & =E^{-1}(0)=m-(-1)^{m+k} k  \tag{8.1-vii}\\
a_{0}+a_{1} & =2 m-1 \tag{8.1-viii}
\end{align*}
$$

Let integers $m \geq 2$ and $k$ be fixed, $\mathcal{V}=\{1, \ldots, 2 m\}$, and $|\mid$ denote cardinality.
Theorem 8.1. There is no set $\varsigma \subseteq \mathcal{V}$ with the following properties:
(a) $a_{1} \in S$ and $\Phi\left(a_{1}\right) \notin S$.
(b) $a_{0} \in \mathcal{S}$ if and only if $m$ is even.
(c) If $a, b \in \mathcal{V}$ and $a+b=2 m+1$, then exactly one of $a$, $b$ lies in $S$.
(d) For every $a \in S \backslash\left\{a_{1}\right\}$ there exists $b \in S$ with $E(b)=-E(a)$.
(e) $|S \cap\{1,2, \ldots, 2 j\}| \leq j$ whenever $j \in\{1, \ldots, m\}$.

Proof. Equivalently, (c) states that $\delta$ is a selector for the $m$-element family $\{\{a, b\} \subseteq$ $\mathcal{V}: a+b=2 m+1\}$. Hence $|\mathcal{S}|=m$. In addition,

$$
\begin{align*}
|S| & =m \geq 3,  \tag{8.2-i}\\
|k| & \leq m-1,  \tag{8.2-ii}\\
\Phi\left(S \backslash\left\{a_{1}\right\}\right) & =S \backslash\left\{a_{1}\right\} . \tag{8.2-iii}
\end{align*}
$$

In fact, as $a_{1} \neq a_{0}$ and $a_{0}+a_{1}=2 m-1$ by (8.1-viii), having $m=2$ in (8.2-i) would, by (a)-(b), give $S=\left\{a_{0}, a_{1}\right\} \subseteq\{1,2,3,4\}$ and $a_{0}+a_{1}=3$, implying that $S=\{1,2\}$, contrary to (e) for $j=1$. Next, (d) and (8.1-v) give $\Phi\left(S \backslash\left\{a_{1}\right\}\right) \subseteq S \backslash\left\{a_{1}\right\}$, cf. (8.1-iii), with the image not containing $a_{1}$, as otherwise, by (8.1-iii), $\Phi\left(a_{1}\right)$ would lie in $\mathcal{S}$, which contradicts (8.1-i); and (8.1-iii) makes the inclusion an equality, proving (8.2-iii). Finally, using (8.2-i), we may fix $a \in S \backslash\left\{a_{1}, 2 m\right\}$. Thus, by (8.2-iii) and (8.1-ii), $1 \leq \Phi(a)=2 m-2(-1)^{a} k-a \leq 2 m$. When $a$ is even (odd) this becomes $2 \leq 2 m-2 k-a \leq 2 m$ (or, $1 \leq 2 m+2 k-a \leq 2 m-1$ ), yielding $1-m \leq k \leq m-2$ (or, $1-m \leq k \leq m-1$ ), and (8.2-ii) follows.

Let us now define $c_{ \pm} \in \mathbb{Z}$ by

$$
\begin{equation*}
c_{ \pm}=m \mp k, \quad \text { so that } 1 \leq c_{ \pm} \leq 2 m-1 \text { due to (8.2-ii) } \tag{8.3}
\end{equation*}
$$

denote by $\mathcal{V}_{ \pm}$(or, $S_{ \pm}$) the set of all $a \in \mathcal{V}$ (or, $a \in S \backslash\left\{a_{1}\right\}$ ) having $(-1)^{a}= \pm 1$ and, finally, given $a, b \in \mathcal{V}_{ \pm}$with $a \leq b$, set $[a, b]_{ \pm}=[a, b] \cap \mathcal{V}_{ \pm}$, referring to any such $[a, b]_{ \pm}$as an even/odd subinterval of $\mathcal{V}$. Finally, we let $\mathcal{R}_{ \pm}$stand for the maximal even/odd subinterval of $\mathcal{V}$ which is symmetric about $c_{ \pm}$. Then

$$
\begin{align*}
& \mathcal{S}=S_{+} \cup S_{-} \cup\left\{a_{1}\right\}, \quad \Phi\left(S_{ \pm}\right)=S_{ \pm}, \quad S_{ \pm} \subseteq \mathcal{R}_{ \pm},  \tag{8.4-i}\\
& \mathcal{R}_{+}=[2,2 m-2 k-2]_{+}, \quad \mathcal{R}_{-}=[2 k+1,2 m-1]_{-} \quad \text { if } k \geq 0,  \tag{8.4-ii}\\
& \mathcal{R}_{+}=[-2 k, 2 m]_{+}, \quad \mathcal{R}_{-}=[1,2 m+2 k-1]_{-} \quad \text { if } k<0, \tag{8.4-iii}
\end{align*}
$$

$\Phi$ restricted to even/odd integers is the reflection about $c_{ \pm}$.

In fact, the first relation in (8.4-i) is obvious, the second immediate from (8.2-iii) since, by (8.1-ii), $\Phi: \mathbb{Z} \rightarrow \mathbb{Z}$ preserves parity. Also, (8.1-ii) yields (8.4-iv), which in turn shows that $S_{ \pm}=\Phi\left(S_{ \pm}\right)$is a (possibly empty) union of sets $\{a, b\}$ having $c_{ \pm}$as the midpoint, and so $\oint_{ \pm} \subseteq \mathcal{R}_{ \pm}$. Finally, depending on whether $c_{ \pm}=m \mp k$ is less (or, greater) than the midpoint $m+1 / 2$ of $\mathcal{V}$, one endpoint of $\mathcal{R}_{ \pm}$must lie in $\{1,2\}$ (or, in $\{2 m-1,2 m\}$ ), and the other endpoint added to this one must yield $2 c_{ \pm}$, which proves (8.4-ii)-(8.4-iii).

Note that, as an obvious consequence of (8.4),
 the lowest $k$ odd and highest $k+1$ even ones when $k>0$, the highest $|k|$ odd and lowest $|k|-1$ even ones for $k<0$, the integer $2 m$ if $k=0$.

Furthermore, one necessarily has

$$
\begin{equation*}
k \in\{0,-1\} \tag{8.6}
\end{equation*}
$$

To see this, we begin by excluding the possibility that $k \geq 2$ (or, $k \leq-3$ ). Namely, if this was the case, (8.5) would give $1,3,2 m-2,2 m \notin S \backslash\left\{a_{1}\right\}$ (when $k \geq 2$ ), or $2,4,2 m-3,2 m-1 \notin S \backslash\left\{a_{1}\right\}$ (for $k \leq-3$ ). From the two pairs $\{1,2 m\},\{3,2 m-2\}$ (or, $\{2,2 m-1\},\{4,2 m-3\}$ ) we would choose one, $\{a, b\}$, having $a_{1} \notin\{a, b\}$ and $a+b=2 m+1$, as well as $a, b \notin S$, which contradicts (c).

The next two cases that need to be excluded are $k=1$ and $k=-2$. If one of them occurred, (8.5) would give $1,2 m \notin S \backslash\left\{a_{1}\right\}$ (if $k=1$ ), or $2,2 m-1 \notin S \backslash\left\{a_{1}\right\}$ (for $k=-2$ ), which would again contradict (c), unless $a_{1} \in\{1,2 m\}$ and $k=1$, or $a_{1} \in\{2,2 m-1\}$ and $k=-2$. However, each of the resulting four possible values $(1,1),(2 m, 1),(2,-2),(2 m-1,-2)$ for the ordered pair $\left(a_{1}, k\right)$ leads, via (8.1-vi), to the immediate conclusion that $m \leq 1$, contrary to (8.2-i), and so (8.6) follows.

As the next step, we write $m=2 j$ ( $m$ even) or $m=2 j+1$ ( $m$ odd), so that $j \geq 1$ by (8.2-i), and proceed to establish the inclusion

$$
\begin{equation*}
S^{\prime} \cup\left\{a_{*}\right\} \subseteq S \cap\{1,2, \ldots, 2 j\}, \quad \text { with }\left|\mathscr{S}^{\prime} \cup\left\{a_{*}\right\}\right|=j+1 \tag{8.7}
\end{equation*}
$$

which will contradict (e), thus completing the proof of the theorem. Here $S^{\prime}$ is the $j$ element set consisting of all integers from $\{1,2, \ldots, 2 j\}$ with a specific parity (even if $k=-1$, odd for $k=0$ ), and $a_{*}=a_{0}(m$ even $)$ or $a_{*}=a_{1}(m$ odd).

To derive (8.7), we list various conclusions in two separate columns (one for either possible value of $k$ ),

$$
\begin{align*}
k & =0, & k & =-1,  \tag{A}\\
\varsigma^{\prime} & =\{1,3, \ldots, 2 j-1\}, & \delta^{\prime} & =\{2,4, \ldots, 2 j\}  \tag{B}\\
a_{*} & =2 j \in S, & a_{*} & =2 j-1 \in S \tag{C}
\end{align*}
$$

$$
\begin{align*}
a_{1} & =m-1, & a_{1} & =m-1+(-1)^{m},  \tag{D}\\
a_{0} & =m, & a_{0} & =m-(-1)^{m}, \\
2 m & \notin S, & 2 m-1 & \notin S, \\
1 & \in S, & 2 & \in S .
\end{align*}
$$

In fact, (B) is the definition of $\Im^{\prime}$, (E), (D), (C) follow from (8.1-vii)-(8.1-viii), with $a_{*} \in S$ due to (a)-(b), while (F) is immediate from (8.5) for $k \in\{-1,0\}$, and (G) from (F) and (c). What still remains to be shown, for (8.7), is the inclusion

$$
\begin{equation*}
\mathscr{S}^{\prime} \subseteq S \tag{8.8}
\end{equation*}
$$

as (8.8) combined with (B)-(C) obviously yields (8.7).
To this end, consider $\Psi: \mathbb{Z} \rightarrow \mathbb{Z}$ given by $\Psi(a)=2 m+1-a$, so that (c) amounts to $|S \cap\{a, \Psi(a)\}|=1$ for all $a \in \mathcal{V}$ or, equivalently, $\Psi(\mathcal{S})=\mathcal{V} \backslash S$ and $\Psi(\mathcal{V} \backslash S)=S$. Now, in our case, given an integer $i$,

$$
\begin{equation*}
\text { if } 1 \leq i<m-2 \text { and } i \in S \text {, then } i+2 \in S . \tag{8.9}
\end{equation*}
$$

Namely, for the sign $\pm$ such that $(-1)^{i}= \pm 1,(8.2$-iii) and (8.4-iv) yield
"in" or "out" meaning lying in $£$ or in $\mathcal{V} \backslash S$. In fact, the four sums of pairs of adjacent integers in the above displayed line are $2(m \mp k)=2 c_{ \pm}, 2 m+1,2(m \pm k)=2 c_{\mp}$, $2 m+1$, as required in the definitions of the reflections $\Psi$ and $\Phi$, the latter restricted to even/odd integers. On the other hand, the inequality $i<m-2$ implies, via (D), that $i \neq a_{1} \neq 2 m-i-1$ (and so $2 m-i-1 \notin S$, for otherwise $i \pm 2 k+1=$ $\Phi(2 m-i-1)$ would lie in $\varsigma)$.

Now (8.9) combined with (G) and (B) proves (8.8) by induction on $i$. Specifically, the highest value of odd (or, even) $i$ such that this yields $i \in S$ is the one with $i-2<$ $m-2 \leq i$, which is the required value $2 j-1$ (or, $2 j$ ) except for even $m$ and $k=-1$. In the latter case, although we get $2 j-2$ instead of $2 j=m$, we have $2 j=m=a_{1} \in S$ nevertheless, due to (D) and (a).

## 9. Proof of Theorem A

We argue by contradiction. Suppose that, for some rank-one ECS model manifold ( $\widehat{M}, \widehat{g}$ ) defined by (4.2), with (4.1), and for G as in Theorem 4.1, there exists a subgroup $\Gamma \subseteq \mathrm{G}$ acting on $\widehat{M}$ freely and properly discontinuously with a generic compact quotient manifold $M=\widehat{M} / \Gamma$,
yet $K_{+}$in (1.2) is infinite cyclic. As $K_{+}=K \cap(0, \infty)$, by Lemma 3.1, for the image $K$ of the homomorphism $\Gamma \ni(q, p, C, r, u) \mapsto q$, we get (3.5b). Theorem 3.3 now allows us to set $I=(0, \infty)$ in (4.1), and all $(q, p, C, r, u) \in \Gamma$ have $p=0$. We fix

$$
\begin{equation*}
\hat{\gamma}=(q, 0, C, \hat{r}, \hat{u}) \in \Gamma \text { such that } q \text { is a generator of } K_{+} . \tag{9.2}
\end{equation*}
$$

From (4.3) and Theorem 4.1, we have (6.3) and $C A C^{-1}=q^{2} A$, for $f, A$ in (4.1). Using the notations of (6.2)-(6.7), with $m=n-2$, we replace $\Gamma$, without loss of generality, by a finite-index subgroup $\Gamma_{+}$, which allows us to assume that

$$
\begin{equation*}
q \in(0, \infty) \backslash\{1\}, C \text { has positive eigenvalues, and } \mu^{ \pm} \in \mathbb{C} \backslash(-\infty, 0] \tag{9.3}
\end{equation*}
$$

Namely, each of these additional requirements amounts to passing from $\Gamma$ to a subgroup of index at most 2 (or, equivalently, from $M$ to the corresponding finite isometric covering). Specifically, we successively intersect $\Gamma$ with the kernels of the homomorphisms $\Gamma \rightarrow\{1,-1\}$ sending $(q, 0, C, r, u)$ to $\operatorname{sgn} q$ and $\operatorname{sgn} C$, the latter sign accounting for positivity or negativity of the eigenvalues of $C$. (According to Corollary 5.3, one of these cases must take place, and all $C$ occurring in G form an Abelian group.) The last condition (positivity of $\mu^{ \pm}$when they are real) is achieved by replacing $\hat{\gamma}, q, C, \mu^{ \pm}$with their squares and $\Gamma$ with the corresponding homomorphic preimage of the index-two subgroup of $K_{+}$generated by $q^{2}$, which is to be done only if $\mu^{ \pm}$are real and negative, cf. (6.6). Finally, we define a linear operator $\Pi: \mathbb{R} \times \mathcal{E} \rightarrow \mathbb{R} \times \mathcal{E}$ by

$$
\begin{equation*}
\Pi(r, u)=(2 \Omega(C T u, \hat{u})+r / q, C T u) \tag{9.4}
\end{equation*}
$$

From the assumption that $K_{+}$is infinite cyclic we will derive, in Lemma 9.2, the existence of a vector subspace $\mathscr{L} \subseteq \mathcal{E}$ having the following properties:

$$
\begin{align*}
& \operatorname{dim} \mathscr{L}=m, \text { where } m=n-2 ;  \tag{9.5-A}\\
& C T \text { leaves } \mathscr{L} \text { invariant; }  \tag{9.5-B}\\
& \Pi\left(\Sigma^{\prime}\right)=\Sigma^{\prime} \text { for some lattice } \Sigma^{\prime} \text { in } \mathbb{R} \times \mathscr{L} ;  \tag{9.5-C}\\
& \Omega\left(u, u^{\prime}\right)=0 \text { whenever } u, u^{\prime} \in \mathscr{L}  \tag{9.5-D}\\
& u \mapsto u(t) \text { is an isomorphism } \mathscr{L} \rightarrow V \text { for every } t \in(0, \infty) \tag{9.5-E}
\end{align*}
$$

Remark 9.1. For any rank-one ECS model manifold (4.1)-(4.2), with $H$ and the solution space $\mathcal{E}$ defined in (4.8) and (4.4), if a vector subspace $\mathscr{L} \subseteq \mathcal{E}$ satisfies (9.5-E), with any $I$ instead of $I=(0, \infty)$, then, restricting (4.9) to $(0, \infty) \times \mathbb{R} \times \mathscr{L}$ we clearly obtain an H -equivariant diffeomorphism

$$
I \times \mathbb{R} \times \mathscr{L} \rightarrow \widehat{M}=I \times \mathbb{R} \times V
$$

its bijectivity being due to ( $9.5-\mathrm{E}$ ), and smoothness of its inverse - to the smooth dependence of the isomorphism $\mathscr{L} \ni u \mapsto u(t) \in V$ on $t$ along with real-analyticity of the isomorphism-inversion operation.

Lemma 9.2. A vector subspace $\mathscr{L} \subseteq \mathcal{E}$ with (9.5) exists if the conditions preceding (9.4) are all satisfied.

Proof. The surjective submersion $\widehat{M} \ni(t, s, v) \mapsto(\log t) /(\log q) \in \mathbb{R}$, being clearly equivariant relative to the homomorphism

$$
\begin{equation*}
\Gamma_{+} \ni \gamma^{\prime}=\left(q^{\prime}, 0, C^{\prime}, r^{\prime}, u^{\prime}\right) \mapsto\left(\log q^{\prime}\right) /(\log q) \in \mathbb{Z} \tag{9.6}
\end{equation*}
$$

along with the obvious actions of $\Gamma$ on $\widehat{M}$, via (4.7) with $p=0$, and $\mathbb{Z}$ on $\mathbb{R}$ by translations, descends to a surjective submersion $M \rightarrow S^{1}$ which is

$$
\begin{equation*}
\text { a bundle projection } \widehat{M} / \Gamma_{+} \rightarrow \mathbb{R} / \mathbb{Z}=S^{1} \tag{9.7}
\end{equation*}
$$

according to Remark 2.3. The kernel $\Sigma$ of (9.6) equals $\Sigma=\{(1,0, \mathrm{Id})\} \times \Sigma^{\prime}$ for some set $\Sigma^{\prime} \subseteq \mathbb{R} \times \mathcal{E}$, since $C^{\prime}$ in (9.6), due to its positivity, (4.3) and Corollary 5.3, is uniquely determined by $q^{\prime}$. Thus, $\Sigma \subseteq \mathrm{H}$, for H given by (4.8). As a consequence of Lemma 3.2 (b) and assertion (f) in Section 4, the restriction to $\Sigma$ of the homomorphism (c) in Section 4 is injective, making $\Sigma$ Abelian. Now (a) in Section 4 implies that the image of $\Sigma^{\prime}$ under the projection $(r, u) \mapsto u$ spans a vector subspace $\mathscr{L} \subseteq \mathcal{E}$ satisfying condition (9.5-D), and so Remark 4.3 gives $\operatorname{dim} \mathscr{L} \leq n-2$. Due to (9.5-D) and (a) in Section $4, \mathrm{H}^{\prime}=\{(1,0, \mathrm{Id})\} \times \mathbb{R} \times \mathscr{L}$ is an Abelian subgroup of H , containing $\Sigma$, and the group operation in $\mathrm{H}^{\prime}$ identified with $\mathbb{R} \times \mathscr{L}$ coincides with the addition in the vector space $\mathbb{R} \times \mathscr{L}$.

At the same time, the (necessarily compact) fiber of the bundle (9.7) over the $\mathbb{Z}$-coset of $(\log t) /(\log q)$ is obviously the quotient $M_{t}=[\{t\} \times \mathbb{R} \times V] / \Sigma$. Compactness of $M_{t}$ implies surjectivity of the linear operator $\mathscr{L} \ni u \mapsto u(t) \in V$ for every $t \in$ $(0, \infty)$, since otherwise a nonzero linear functional vanishing on its image, composed with the projection $\{t\} \times \mathbb{R} \times V \rightarrow V$, would descend - according to (b) in Section 4 to an unbounded function $M_{t} \rightarrow \mathbb{R}$. Thus, $\operatorname{dim} \mathscr{L} \geq n-2=\operatorname{dim} V$ which, due to the opposite inequality in the last paragraph, gives both (9.5-A) and (9.5-E). Remark 9.1 with $I=(0, \infty)$ and the italicized conclusion of the preceding paragraph, combined with compactness of each of the quotients $M_{t}$ (and the obvious proper discontinuity of the action of $\Sigma$ on $\{t\} \times \mathbb{R} \times V$ ) show that $\Sigma^{\prime}$ is a lattice in $\mathbb{R} \times \mathscr{L}$.

Finally, according to Remark 4.2, the right-hand side of (9.4) describes the conjugation by our $\hat{\gamma}$ in (9.2) applied to $(1,0, \mathrm{Id}, r, u) \in \Sigma$, which we identify here with $(r, u)$. As this conjugation obviously sends the kernel $\Sigma$ onto itself, we get (9.5-C), and so $\Pi(\mathbb{R} \times \mathscr{L})=\mathbb{R} \times \mathscr{L}$ (since $\Sigma^{\prime}$ is a lattice in $\mathbb{R} \times \mathscr{L}$ ). Now (9.4) yields (9.5-B), which completes the proof.

Lemma 9.3. Under the hypotheses preceding (9.4), let a vector subspace $\mathscr{L} \subseteq \mathcal{E}$ satisfy (9.5-A)-(9.5-C), a basis $u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}$of $\mathcal{E}^{\mathbb{C}}$ containing a basis $u_{1}, \ldots, u_{m}$ of $\mathscr{L}^{\mathbb{C}}$ be chosen as in Theorem 6.1, and $\lambda_{1}, \ldots, \lambda_{m}$ be the corresponding complex characteristic roots of $C T: \mathcal{E} \rightarrow \mathcal{E}$ selected from $\lambda_{1}^{+}, \lambda_{1}^{-}, \ldots, \lambda_{m}^{+}, \lambda_{m}^{-}$given by (6.9). Then
(i) $\quad \lambda_{0}=q^{-1}$ and $\lambda_{1}, \ldots, \lambda_{m}$ form a $\mathrm{GL}(\mathbb{Z})$-spectrum,
in the sense that they are the complex roots of some $\mathrm{GL}(\mathbb{Z})$-polynomial of degree $m+1$, defined as in Section 7, and
(ii) the product $\lambda_{1} \cdots \lambda_{m}$ equals $q$ or $-q$.

Furthermore, assuming in addition that
(iii) one of $\mu^{ \pm}$is a power of $q$ with a rational exponent,
we have the following conclusions:
(iv) Both $\mu^{ \pm}$are powers of $q$ with integer exponents.
(v) $\lambda_{1}^{+}, \lambda_{1}^{-}, \ldots, \lambda_{m}^{+}, \lambda_{m}^{-}$are all distinct, real and positive.
(vi) Exactly one of $\lambda_{1}, \ldots, \lambda_{m}$ equals $q$.
(vii) Just one, or none of $\lambda_{1}, \ldots, \lambda_{m}$ equals 1 if $n$ is even, or odd.
(viii) Those $\lambda_{1}, \ldots, \lambda_{m}$ not equal to $q$ or 1 form pairs of mutual inverses.
(ix) $\Omega\left(u_{i}^{ \pm}, u_{j}^{ \pm}\right)=0$ for all $i, j \in\{1, \ldots, m\}$ and both signs $\pm$.
(x) $\Omega\left(u_{i}^{ \pm}, u_{j}^{\mp}\right) \neq 0$ if and only if $i+j=m+1$.

Proof. Assertion (i) is immediate from (9.4) and (9.5-C) along with (7.1), and (ii) from (i). Assuming (iii), we see - using (6.9), (6.6) and (7.3) - that, for the GL( $\mathbb{Z}$ )polynomial $P$ with the roots $\lambda_{0}, \ldots, \lambda_{m}$,
(xi) the irreducible factors of $P$ must all be linear or quadratic,
higher degree cyclotomic polynomials being excluded since the roots are all real. Thus, one of $\lambda_{1}, \ldots, \lambda_{m}$ equals $q$, to match $\lambda_{0}=q^{-1}$, and (6.9) combined with (6.6) yields (iv). Since $\left|\lambda_{j}^{ \pm}\right|$is, for either sign $\pm$, a strictly monotone function of $j$, to prove (v) it suffices to consider the case $q^{m+1-2 j} \mu^{ \pm}=q^{m+1-2 i} \mu^{\mp}$, that is, $\mu^{ \pm} / \mu^{\mp}=$ $q^{2(j-i)}$. Multiplied by $\mu^{ \pm} \mu^{\mp}=q^{-1}$, cf. (6.6), this makes $\left(\mu^{ \pm}\right)^{2}$ a power of $q$ with an odd integer exponent, contrary to (iv), so that (v) follows. From (iii) and (xi) we now get (viii).

For our basis $u_{j}^{ \pm}$of $\mathcal{E}$, diagonalizing $C T$ with the eigenvalues $\lambda_{j}^{ \pm}=q^{m+1-2 j} \mu^{ \pm}$, (g) in Section 4 gives

$$
\begin{aligned}
& q^{-1} \Omega\left(u_{i}^{ \pm}, u_{j}^{ \pm}\right)=q^{2 m+2-2 i-2 j}\left(\mu^{ \pm}\right)^{2} \Omega\left(u_{i}^{ \pm}, u_{j}^{ \pm}\right), \\
& q^{-1} \Omega\left(u_{i}^{ \pm}, u_{j}^{\mp}\right)=q^{2 m+2-2 i-2 j} \mu^{+} \mu^{-} \Omega\left(u_{i}^{ \pm}, u_{j}^{\mp}\right)
\end{aligned}
$$

Thus, the inequality $\Omega\left(u_{i}^{ \pm}, u_{j}^{ \pm}\right) \neq 0$ would, again, make $\left(\mu^{ \pm}\right)^{2}$ a power of $q$ with an odd integer exponent, contradicting (iv), which yields (ix). Similarly, assuming that $\Omega\left(u_{i}^{ \pm}, u_{j}^{\mp}\right) \neq 0$, we now get, from (6.6), $i+j=m+1$. The converse implication needed in (x) follows, via (ix), from nondegeneracy of $\Omega$.

Lemma 9.4. With the assumptions and notations of Lemma 9.3, let $\mathscr{L}$ this time satisfy all of (9.5). Then conditions (i)-(x) in Lemma 9.3 all hold, so that $\mu^{ \pm}$and $\lambda_{j}^{ \pm}$are all real, while
(i) the number of pluses is different from that of minuses
among the $\pm$ superscripts of those $\lambda_{1}^{+}, \lambda_{1}^{-}, \ldots, \lambda_{m}^{+}, \lambda_{m}^{-}$which form the characteristic roots $\lambda_{1}, \ldots, \lambda_{m}$ of $C T: \mathscr{L} \rightarrow \mathscr{L}$. Finally, for the basis $\mathfrak{B}=\left\{u_{1}, \ldots, u_{m}\right\}$ of $\mathscr{L}$ contained in the basis $\left\{u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}\right\}$of $\mathcal{E}$, with $|\mid$ denoting cardinality,
(ii) $\left|\mathfrak{B} \cap\left\{u_{1}^{+}, u_{1}^{-}, \ldots, u_{j}^{+}, u_{j}^{-}\right\}\right| \leq j$ whenever $j=1, \ldots, m$,
(iii) $\left|\mathscr{B} \cap\left\{u_{i}^{+}, u_{j}^{-}\right\}\right|=1$ if $i, j \in\{1, \ldots, m\}$ and $i+j=m+1$.

Proof. If (ii) failed to hold, the evaluation operator in (9.5-E), complexified if necessary, would send $\left\{u_{1}, \ldots, u_{j+1}\right\}$ into the span of the vectors $e_{1}, \ldots, e_{j}$ appearing in (6.9), contrary to its injectivity. From (ii) we obtain
(iv) $k(j) \geq j$ for all $j=1, \ldots, m$,
$k(j) \in\{1, \ldots, m\}$ being such that $u_{j}=u_{k(j)}^{ \pm}$with some sign $\pm$, since, otherwise, $\mathscr{B} \cap\left\{u_{1}^{+}, u_{1}^{-}, \ldots, u_{k(j)}^{+}, u_{k(j)}^{-}\right\}$would have at least $j>k(j)$ elements.

To prove (i), we now assume its negation, and evaluate the product of those $\lambda_{j}^{ \pm}=$ $q^{m+1-2 j} \mu^{ \pm}$in (6.9) which constitute $\lambda_{1}, \ldots, \lambda_{m}$. Both factors $\mu^{+}, \mu^{-}$appear in this product the same number of times, $m / 2$, which makes $m$ even, and by (6.6) their occurrences contribute to our product $\lambda_{1} \cdots \lambda_{m}$ a total factor of $q^{-m / 2}$. On the other hand, the set $\left\{q^{m+1-2 j}: 1 \leq j \leq m\right\}=\left\{q^{m-1}, q^{m-3}, \ldots, q^{1-m}\right\}$ is closed under taking inverses, so that $\prod_{j=1}^{m} q^{m+1-2 j}=1$. Writing $k(j)=j+\ell(j)$, with $\ell(j) \geq 0$ due to (iv), we now have

$$
\begin{equation*}
\lambda_{j}=\lambda_{k(j)}^{ \pm}=q^{m+1-2 k(j)} \mu^{ \pm}=q^{m+1-2 j} \mu^{ \pm} q^{-2 \ell(j)} \tag{9.8}
\end{equation*}
$$

making $\lambda_{1} \cdots \lambda_{m}$ equal to 1 times $q^{-m / 2}$ times $\prod_{j=1}^{m} q^{-2 \ell(j)}$, that is, a power of $q$ with a negative exponent, contrary to Lemma 9.3 (ii).

Next, (i) implies that $\mu^{ \pm}$and $\lambda_{j}^{ \pm}$are all real, for otherwise $\lambda_{j}$ in (9.8), forming along with $\lambda_{0}=q^{-1}$ the spectrum of a real matrix, would come in nonreal conjugate pairs, with the same number of positive real parts as negative ones. Thus, by (9.3), $\mu^{ \pm}>0$. Using (i) and reality of $\mu^{ \pm}$we now evaluate the product $\lambda_{1} \cdots \lambda_{m}= \pm q$ in Lemma 9.3 (ii), observing that not all $\mu^{+}, \mu^{-}$undergo pairwise "cancellations" (forming the product $q^{-1}$ ), but instead Lemma 9.3 (ii) equates some power of $\mu^{+}$
or $\mu^{-}$, with a positive integer exponent, to a power of $q$, and so positivity of $\mu^{ \pm}$ yields condition (iii) in Lemma 9.3, which in turn implies (iv)-(x).

Finally, the $m$-element family $\mathcal{P}=\left\{\left\{u_{i}^{+}, u_{j}^{-}\right\}: i+j=m+1\right\}$ forms a partition of $\left\{u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}\right\}$into disjoint two-element subsets, while the mapping $F$ : $\mathscr{B} \rightarrow \mathscr{P}$ given by $u \in F(u)$ is injective: $\left|\mathscr{B} \cap\left\{u_{i}^{+}, u_{j}^{-}\right\}\right| \leq 1$ if $i+j=m+1$, or else Lemma 9.3 (x) would contradict (9.5-D). As $|\mathscr{B}|=m$, surjectivity of $F$ thus follows, proving (iii).

We now complete the proof of Theorem A by observing that a vector subspace $\mathscr{L} \subseteq \mathcal{E}$ with (9.5) gives rise to a subset $S$ of $\mathcal{V}=\{1, \ldots, 2 m\}$, for $m=n-2$, satisfying conditions (a)-(e) in Theorem 8.1, which - according to Theorem 8.1 - cannot exist. Namely, using Lemma 9.3 (iv) we define $k \in \mathbb{Z}$ by $\mu^{+}=q^{k}$, so that, by (6.6), $\mu^{-}=$ $q^{-k-1}$. Next, the obvious order-preserving bijection

$$
\begin{equation*}
\mathcal{V}=\{1, \ldots, 2 m\} \rightarrow\left\{u_{1}^{+}, u_{1}^{-}, \ldots, u_{m}^{+}, u_{m}^{-}\right\} \tag{9.9}
\end{equation*}
$$

(notation of Lemma 9.3) which, explicitly, sends $a \in \mathcal{V}$ to $u_{j}^{-}$when $a=2 j$ is even, or to $u_{j}^{+}$for odd $a=2 j-1$, is used from now on to identify the two sets, and we declare $S$ to be the subset of $\mathcal{V}$ corresponding under (9.9) to the basis $\mathscr{B}=\left\{u_{1}, \ldots, u_{m}\right\}$ of $\mathscr{L}$. The function assigning to each $u_{j}^{ \pm}$the corresponding eigenvalue $\lambda_{j}^{ \pm}=q^{m+1-2 j} \mu^{ \pm}$ treated, via (9.9), as defined on $\mathcal{V}$, is now easily seen to be given by $\mathcal{V} \ni a \mapsto q^{E(a)}$, with (8.1-i). Referring to (a)-(e) in Theorem 8.1 simply as (a)-(e), we observe that assertions (ii) and (iii) of Lemma 9.4 yield (e) and (c), while (b), the first claim in (a), and (d) trivially follow from Lemma 9.3 (vi)-(viii) (the latter guaranteed to hold by Lemma 9.4). Finally, the relation $\Phi\left(a_{1}\right) \notin S$ in (a) which, in view of (8.1-iii) and (8.1-v), amounts to $q^{-1} \notin\left\{\lambda_{1}, \ldots, \lambda_{m}\right\}$, is thus immediate since otherwise, due to Lemma 9.3 (viii), the inverse $q$ of $q^{-1}$ would occur on the list $\lambda_{1}, \ldots, \lambda_{m}$ twice, contradicting Lemma 9.3 (v).

Acknowledgments. The authors wish to thank the anonymous referee, whose suggestions helped us improve the exposition.

Funding. The first author's research was supported in part by a FAPESP-OSU 2015 Regular Research Award (FAPESP grant: 2015/50265-6).

## References

[1] A. Derdziński, On conformally symmetric Ricci-recurrent manifolds with Abelian fundamental groups. Tensor (N.S.) $\mathbf{3 4}$ (1980), no. 1, 21-29 Zbl 0438.53046 MR 570559
[2] A. Derdziński and W. Roter, On conformally symmetric manifolds with metrics of indices 0 and 1. Tensor (N.S.) 31 (1977), no. 3, 255-259 Zbl 0379.53027 MR 467596
[3] A. Derdzinski and W. Roter, Global properties of indefinite metrics with parallel Weyl tensor. In Pure and applied differential geometry-PADGE 2007, pp. 63-72, Ber. Math., Shaker Verlag, Aachen, 2007 Zbl 1140.53034 MR 2497674
[4] A. Derdzinski and W. Roter, The local structure of conformally symmetric manifolds. Bull. Belg. Math. Soc. Simon Stevin 16 (2009), no. 1, 117-128 Zbl 1165.53011 MR 2498963
[5] A. Derdzinski and W. Roter, Compact pseudo-Riemannian manifolds with parallel Weyl tensor. Ann. Global Anal. Geom. 37 (2010), no. 1, 73-90 Zbl 1193.53147 MR 2575471
[6] A. Derdzinski and I. Terek, New examples of compact Weyl-parallel manifolds. 2022, arXiv:2210.03660, to appear in Monatsh. Math.
[7] A. Derdzinski and I. Terek, The topology of compact rank-one ECS manifolds. Proc. Edinb. Math. Soc. 66 (2023), no. 3, 789-809
[8] A. Derdzinski and I. Terek, Compact locally homogeneous manifolds with parallel Weyl tensor. 2023, arXiv:2306.01600
[9] A. Derdzinski and I. Terek, The metric structure of compact rank-one ECS manifolds. 2023, arXiv:2304.10388, to appear in Ann. Global Anal. Geom.
[10] B. I. Dundas, A short course in differential topology. Cambridge Math. Textbooks, Cambridge University Press, Cambridge, 2018 Zbl 1397.57001 MR 3793640
[11] H. Maier, Anatomy of integers and cyclotomic polynomials. In Anatomy of integers, pp. 89-95, CRM Proc. Lecture Notes 46, American Mathematical Society, Providence, RI, 2008 Zbl 1186.11010 MR 2437967
[12] Z. Olszak, On conformally recurrent manifolds, I: Special distributions. Zesz. Nauk. Politech. Śl., Mat.-Fiz. 68 (1993), 213-225 Zbl 0841.53033
[13] W. Roter, On conformally symmetric Ricci-recurrent spaces. Colloq. Math. 31 (1974), 87-96 Zbl 0292.53014 MR 372768

Received 25 January 2023; revised 9 June 2023.

## Andrzej Derdzinski

Department of Mathematics, The Ohio State University, 231 W. 18th Avenue, Columbus,
OH 43210, USA; andrzej@math.ohio-state.edu

## Ivo Terek

Department of Mathematics, The Ohio State University, 231 W. 18th Avenue, Columbus, OH 43210, USA; terekcouto. 1 @osu.edu

