

Legendrian and transverse knobs and
their invariants

UIC Colloquium at
Knots in Chicago

Sept. 10, 2010

3pm - 4pm.

- 1) Contact structure
- 2) Low dimensional contact topology
- 3) Legendrian knots
- 4) Transverse knots

① Contact structure

[M^m is a smooth manifold]

is a maximal non-integrable field of tangent hyperplanes $H_x \subset T_x M$

$$H_x = \{ \vec{v} \in T_x M : \alpha(\vec{v}) = 0 \} \text{ where } \alpha \in S^1(M)$$

non-integrability: $d\alpha|_{H_x}$ is a non-degenerate bilinear form

Maximal integrable manifold has dimension n (Legendrian manifolds)

\Downarrow
 $m = 2n + 1$ $\underbrace{d\alpha|_{H_x} \dots d\alpha|_{H_x}}_n \neq 0$

Darboux Theorem

\exists local coordinates $x_1, \dots, x_n, y_1, \dots, y_n, z$ such that $\alpha = \sum y_i dx_i - dz$

$$H_x = \{ dz = \sum y_i dx_i \}$$

Standard contact \mathbb{R}^{2n+1} : $\alpha = \sum y_i dx_i - dz$

Contact topology:
 top: $\textcircled{\circ}$ homeomorphism
 dif. top: $\textcircled{\circ}$ diffeomorphism
 $\textcircled{\circ}$ contactomorphism

② Low dimensional contact topology $n=1$

Standard contact \mathbb{R}^3 : $\alpha = y dx - dz$

~~$y = \frac{dz}{dx}$~~

$z = f(x)$

\downarrow 1-graph

$(x, f(x), f'(x))$ Legendrian curve

(1)

Rotational standard contact structure

$$\alpha_{\text{rot}} = dz - y dx + x dy$$

Exercise Find a contactomorphism that sends α_{rot} to α_{std}

Answer $(x, y, z) \rightarrow (-x, 2y, -xy - z)$

$$\alpha_{\text{std}} = 2y d(-x) - d(-xy - z) =$$

$$= \underbrace{-2y dx} + xy dy + \underbrace{y dx} + dz = \alpha_{\text{rot}}$$

Contact Bundle $\{H_x\} \subset TM$



Standard contact \mathbb{R}^{2n+1} is parallelizable
 $\mathbb{R}^5 = \mathbb{R}^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2 \rightarrow S^1$
 \downarrow
 \mathbb{R}^3

③ Legendrian knots $L \subset \mathbb{R}^3$

Unit tangent vectors

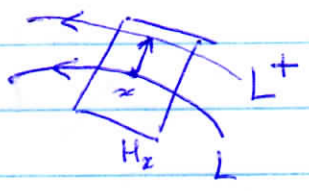
$$L = \{ S^1 \rightarrow \mathbb{R}^3 \} \xrightarrow{\mu} S^1 \subset \mathbb{R}^2$$

Maslov number $m := \deg \mu$

Thurston - Bennequin number: $tb(L) = lk(L, L^+)$

$\alpha \wedge d\alpha \rightarrow$ orientation of \mathbb{R}^3
 $d\alpha \rightarrow$ orientation of H_x

Legendrian framing



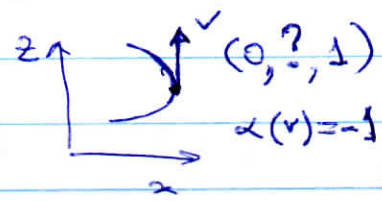
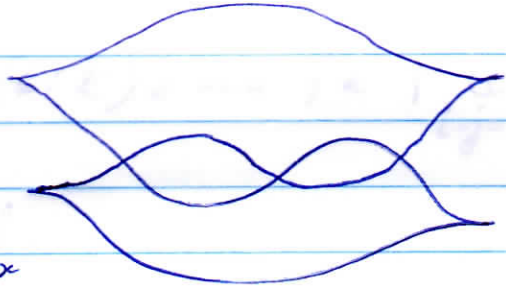
(Front)

③ Diagrams of Legendrian knots

\mathbb{R}^3
(x, y, z)

$\alpha = ydx - dz$

\downarrow
 \mathbb{R}^2
x, z

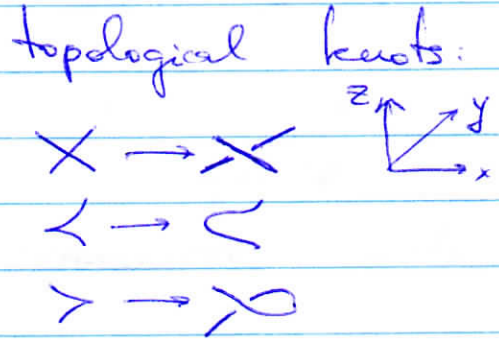
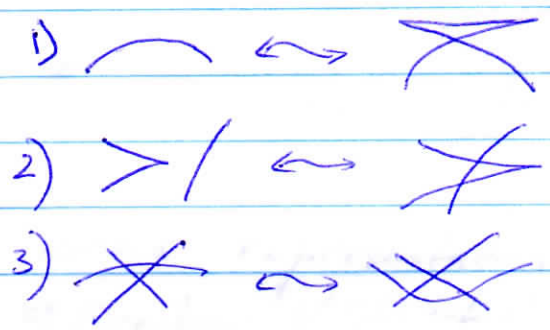


$m = \# \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) + \# \left(\begin{array}{c} \nwarrow \\ \swarrow \end{array} \right) - \# \left(\begin{array}{c} \nearrow \\ \swarrow \end{array} \right) - \# \left(\begin{array}{c} \nwarrow \\ \searrow \end{array} \right)$

$tb = \# \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) + \# \left(\begin{array}{c} \nwarrow \\ \swarrow \end{array} \right) - \# \left(\begin{array}{c} \nearrow \\ \swarrow \end{array} \right) - \# \left(\begin{array}{c} \nwarrow \\ \searrow \end{array} \right) - \# \left(\begin{array}{c} > \\ < \end{array} \right)$

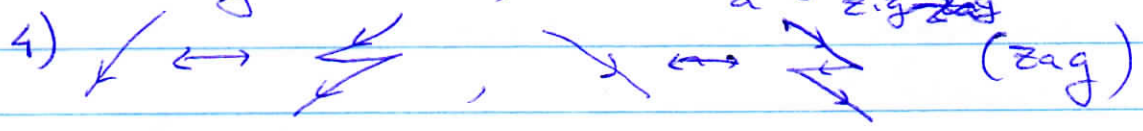
left cusps

Legendrian isotopy (Reidemeister moves)



D. Fuchs, S. Tabachnikov 197:

Two top. knots given by Leg. fronts are equivalent iff the ~~two~~ fronts are related by 1-3) and by adding (or removing) a zigzag



F. Aicardi's move, Chekanov's move

Estimates for $tb(K)$

- V. Goryunov '97

$tb(K) < \text{max deg of } x \text{ in } F(x, y)$

Khovanov homology:

L. Ng '05

$tb(K) < \min \{k \mid \bigoplus_{i-j=k} HKh^{i,j}(K) \neq 0\}$

Grid diagrams

② Transverse knots is a knot

transversal to the contact structure

Example (1) unit circle in (x, y) -plane is α -rot.

(2) L^+ is transverse (Leg. Reidemeister + Zag 4)

Bennequin '83 : $tb(L^+) = tb(L) + m(L)$
Legendrian L

Braid representation for transverse knots.

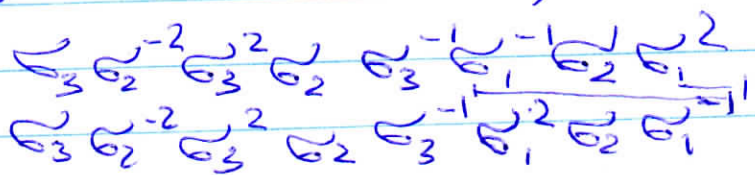
S. Orevkov, V. Shevchishin '08

N. Wrinkle '02

Transverse Markov theorem

$B_1 \sim_{\text{tran}} B_2$ iff B_1 and B_2 are related by a sequence of braid conjugations and positive braid stabilizations/destabilizations

P. Ozsváth, Z. Szabo, D. Thurston '06



$\Theta \in \widehat{HFK}$

0. Plamenovskaya '04

$\psi(L) \in H^1(L)$ is a transverse invariant.