

Borel Summability in PDE initial value problems

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Main idea

For an autonomous differential operator \mathcal{N} , consider

$$v_t = \mathcal{N}[v] , \quad v(x, 0) = v_0(x)$$

Formal small time expansion:

$$\tilde{v}(x, t) = v_0(x) + tv_1(x) + t^2v_2(x) + \dots,$$

where $v_1(x) = \mathcal{N}[v_0](x)$, $v_2 = \frac{1}{2} \{ \mathcal{N}_v(v_0)[v_1] \} (x), \dots$

Generically divergent if order of \mathcal{N} is greater than 1

If Borel summable, obtain

$$v(x, t) = \sum_B \tilde{v},$$

solution to the PDE initial value problem for small enough time.

Depending on properties in the Borel plane, solution can be extended over longer time periods $[0, T]$.

Eg: 1-D Heat Equation (Lutz, Miyake & Schaefke)

$$v_t = v_{xx}, \quad v(x, 0) = v_0(x), \quad v(x, t) = v_0 + tv_1 + ..$$

Obtain recurrence relation

$$(k + 1)v_{k+1} = v_k'', \quad \text{implies } v_k = \frac{v_0^{(2k)}}{k!}$$

Unless v_0 entire, series $\sum_k t^k v_k$ factorially divergent.

Borel transform in $\tau = 1/t$: $V(x, p) = \mathcal{B}[v(x, 1/\tau)](p)$,

$V(x, p) = p^{-1/2} W(x, 2\sqrt{p})$, then $W_{qq} - W_{xx} = 0$

Obtain $v(x, t) = \int_{\mathbb{R}} v_0(y) (4\pi t)^{-1/2} \exp[-(x - y)^2 / (4t)] dy$,

i.e. Borel sum of formal series leads to usual heat solution.

We seek applications of these simple ideas to more complicated

PDEs, including 3-D Navier-Stokes

Background

Borel Summability for linear PDEs studied before (Balsler, Miyake, Lutz, Schaefer, ..)

Sectorial existence for a class of nonlinear PDEs (Costin & T.)

Complex singularity formation for a nonlinear PDE (Costin & T.)

Navier Stokes is a nonlinear PDE governing fluid velocity $v(x, t)$:

$$v_t + v \cdot \nabla v = -\nabla P + \nu \Delta v + f$$

$$\nabla \cdot v = 0, \quad v(x, 0) = v_0(x)$$

Using PDE techniques, Leray (1930s) proved local existence, uniqueness for classical solutions and global existence for weak solutions. Global existence of classical solutions known in 2-D, not in 3-D. Literature extensive (Constantin, Temam, Foias,...).

Background II

Global existence of classical solution or lack of it has fundamental implications to fluid turbulence.

Blow up of classical solution with finite energy $\|v_0\|_{L^2(\mathbb{R}^3)}$ implies $\|\nabla \times v(\cdot, t)\|_\infty$ and $\|v(\cdot, t)\|_{L^3(\mathbb{R}^3)}$ blow up (Beale *et al*, Sverak).

This becomes incompatible with the modeling assumptions in deriving Navier-Stokes. Hence other parameters not included in Navier-Stokes would become important in turbulent flow.

For the usual PDE techniques, key to global existence question is believed to be *a priori* energy bounds involving ∇v (Tao). None is available thus far.

This motivates alternate formulation of initial value problems for nonlinear PDEs that are not dependent on energy bounds at all. Borel methods and generalization via *Ecal* sum allows this.

Illustration: Borel Transform for Burger's equation

Substitute $v = v_0(x) + u(x, t)$ into $v_t + vv_x = v_{xx}$ to obtain

$$u_t - u_{xx} = -v_0 u_x - uv_{0,x} - uu_x + v_1(x)$$

where $v_1(x) = v_0'' - v_0 v_{0,x}$, and $u(x, 0) = 0$

Inverse Laplace Transform in $1/t$ and Fourier-Transform in x :

$$p\hat{U}_{pp} + 2U_p + k^2\hat{U} = \hat{v}_1 - ik\hat{v}_0 \hat{*}\hat{U} - ik\hat{U} \hat{*}_*\hat{U} \equiv \hat{G}(k, p) + \hat{v}_1,$$

$\hat{*}$ is Fourier convolution, $\hat{*}_*$ Fourier-Laplace convolution. Hence

$$\hat{U}(k, p) = \int_0^p \mathcal{K}(p, p'; k) \hat{G}(k, p') dp' + \hat{U}^{(0)}(k, p) \equiv \mathcal{N}[\hat{U}](k, p)$$

$$\mathcal{K}(p, p'; k) = \frac{ik\pi}{z} \{z'Y_1(z')J_1(z) - z'Y_1(z)J_1(z')\}$$

$$z = 2|k|\sqrt{p}, \quad z' = 2|k|\sqrt{p'}, \quad \hat{U}^{(0)}(k, p) = 2\frac{J_1(z)}{z}\hat{v}_1(k)$$

Solution to integral equation $\hat{U} = \mathcal{N}[\hat{U}]$

We find $|\mathcal{K}(p, p'; k)| \leq \frac{C}{\sqrt{p}}$, C a constant

$$\|\hat{F}(\cdot, p) \hat{*} \hat{G}(\cdot, p)\|_{L^1(\mathbb{R})} \leq C \|\hat{F}(\cdot, p)\|_{L^1(\mathbb{R})} \|\hat{G}(\cdot, p)\|_{L^1(\mathbb{R})}$$

Define norm $\|\cdot\|^{(\alpha)}$ for functions $F(p, k)$

$$\|F\|^{(\alpha)} = \int_0^\infty e^{-\alpha p} \|F(\cdot, p)\|_{L^1(\mathbb{R})} dp$$

easily follows $\|F \hat{*} G\|^{(\alpha)} \leq C \|F\|^{(\alpha)} \|G\|^{(\alpha)}$

\mathcal{N} seen to be contractive for large α implies Burgers solution for $\text{Re } \frac{1}{t} > \alpha$ in the form $v(x, t) = v_0(x) + \int_0^\infty e^{-p/t} U(x, p) dp$

Global classical PDE solution implied if $\|\hat{U}(\cdot, p)\|_{L^1(\mathbb{R}^3)}$ bounded.

Borel summability for analytic v_0 requires analyticity of $U(\cdot, p)$ for $p \in 0 \cup \mathbb{R}^+$; proof a bit more delicate.

Incompressible 3-D Navier-Stokes in Fourier-Space

Consider 3-D N-S in infinite geometry or periodic box. Similar results expected for finite domain with no-slip BC using eigenfunctions of Stokes operator as basis. In Fourier-Space

$$\hat{v}_t + \nu |k|^2 \hat{v} = -ik_j P_k [\hat{v}_j \hat{*} \hat{v}] + \hat{f}(k)$$

$$P_k = \left(I - \frac{k(k \cdot)}{|k|^2} \right) , \quad \hat{v}(k, 0) = \hat{v}_0(k)$$

where P_k is the Hodge projection in Fourier space, $\hat{f}(k)$ is the Fourier-Transform of forcing $f(x)$, assumed divergence free and t -independent. Subscript j denotes the j -th component of a vector. $k \in \mathbb{R}^3$ or \mathbb{Z}^3 . Einstein convention for repeated index followed. $\hat{*}$ denotes Fourier convolution.

Integral equation for Navier Stokes in Borel plane

Substitute $\hat{v} = \hat{v}_0 + \hat{u}(k, t)$, into Navier-Stokes, inverse-Laplace Transform in $1/t$ and inverting as for Burger's equation obtain integral equation:

$$U(k, p) = \int_0^p \mathcal{K}(p, p') \hat{R}(k, p') dp' + U^{(0)}(k, p),$$

$$\hat{R}(k, p) = -ik_j P_k \left[\hat{v}_{0,j} \hat{*} \hat{U} + \hat{U}_j \hat{*} \hat{v}_0 + \hat{U}_j \hat{*} \hat{U} \right]$$

$$U^{(0)}(k, p) = 2 \frac{J_1(z)}{z} \hat{v}_1(k), \quad \text{where}$$

$$\hat{v}_1(k) = -|k|^2 \hat{v}_0 - ik_j P_k [\hat{v}_{0,j} \hat{*} \hat{v}_0] + \hat{f}(k)$$

Some Results for Navier-Stokes (NS) in \mathbb{R}^3

Define $\|\cdot\|_{\mu,\beta}$, for $\mu > 3, \beta \geq 0$:

$$\|v_0\|_{\mu,\beta} = \sup_{k \in \mathbb{R}^3} e^{\beta|k|} (1 + |k|)^\mu |\hat{v}_0(k)|$$

Theorem 1: If $\|f\|_{\mu,\beta}, \|\hat{v}_0\|_{\mu+2,\beta} < \infty$, NS has unique solution with $\|\hat{v}(\cdot, t)\|_{\mu,\beta} < \infty$ for $\operatorname{Re} \frac{1}{t} > \alpha$, where α depends on \hat{v}_0, \hat{f} . Furthermore, $\hat{v}(\cdot, t)$ is analytic for $\operatorname{Re} \frac{1}{t} > \alpha$ and $\|\hat{v}(\cdot, t)\|_{\mu+2,\beta} < \infty$ for $t \in [0, \alpha^{-1})$. For $\beta > 0$, v is analytic in x with same analyticity width as v_0 and f .

Theorem 2: For $\beta > 0$, the NS solution v is Borel summable in $1/t$, i.e. there exists $U(x, p)$, analytic in a neighborhood of \mathbb{R}^+ , exponentially bounded, and analytic in x for $|\operatorname{Im} x| < \beta$ so that $v(x, t) = v_0(x) + \int_0^\infty U(x, p) e^{-p/t} dp$. When $t \rightarrow 0$, $v(x, t) \sim v_0(x) + \sum_{m=1}^\infty t^m v_m(x)$, where $|v_m(x)| \leq m! A_0 B_0^m$, with A_0, B_0 generally dependent on v_0, f .

Same results in \mathbb{T}^3 . Further, when v_0, f_0 have finite Fourier modes, B_0 is independent of initial data and f_0 .

Results on Navier-Stokes in \mathbb{T}^3

Define $\|\cdot\|^{(\alpha)}$ so that

$$\|\hat{V}\|^{(\alpha)} = \int_0^\infty e^{-\alpha p} \|\hat{V}(\cdot, p)\|_{l^1(\mathbb{Z}^3)} dp$$

Theorem 3: If $\|\hat{v}_0\|_{l^1(\mathbb{Z}^3)}, \|\hat{f}\|_{l^1(\mathbb{Z}^3)} < \infty$ then there exists some $\alpha > 0$ so that integral equation $\hat{U} = \mathcal{N}[\hat{U}]$ has a unique solution for $p \in \mathbb{R}^+$ in the space of functions $\{\hat{U} : \|\hat{U}\|^{(\alpha)} < \infty\}$. Further,

$\hat{v}(k, t) = \hat{v}_0(k) + \int_0^\infty \hat{U}(k, p) e^{-p/t} dp$ satisfies 3-D Navier-Stokes in Fourier-Space; corresponding $v(x, t)$ is a classical NS solution for $t \in (0, \alpha^{-1})$.

Remark 1: Classical PDE methods known to give similar results. However, in the present formulation, global PDE existence is a question of asymptotics of known solution to integral equation as $p \rightarrow \infty$. Sub-exponential growth implies global existence.

More Remarks on Theorem 3 for 3-D Navier-Stokes

Remark 2: Errors in Numerical solutions rigorously controlled.
Discretization in p and Galerkin approximation in k results in:

$$\begin{aligned}\hat{U}_\delta(k, m\delta) &= \delta \sum_{m'=0}^m \mathcal{K}_{m,m'} \mathcal{P}_N \mathcal{H}_\delta(k, m'\delta) + \hat{U}^{(0)}(k, m\delta) \\ &\equiv \mathcal{N}_\delta \left[\hat{U}_\delta \right] \quad \text{for } k_j = -N, \dots, N, \quad j = 1, 2, 3\end{aligned}$$

\mathcal{P}_N is the Galerkin Projection into N -Fourier modes. \mathcal{N}_δ has properties similar to \mathcal{N} . The continuous solution \hat{U} satisfies $\hat{U} = \mathcal{N}_\delta \left[\hat{U} \right] + E$, where E is the truncation error. Thus, $\hat{U} - \hat{U}_\delta$ can be estimated using same tools as in Theorem 1.

Note: Similar control over discretized solutions to PDEs not available since truncation errors involve derivatives of PDE solution which are not known to exist beyond a short-time.

Extending Navier-Stokes interval of existence

Suppose $\hat{U}(\cdot, p)$ is known over $[0, p_0]$ through Taylor series in p or otherwise, and computed $\|\hat{U}(\cdot, p)\|_{l^1}$ is observed to decrease towards the end of this interval. Prior discussions show that any error in this computation can be rigorously controlled.

Results in the following page show that a more optimal Borel exponent $\alpha \leq \alpha_0$ may be estimated using the known solution in $[0, p_0]$, where α_0 is the initial α estimate in Theorem 1. This implies a longer interval $[0, \alpha^{-1})$ for NS solution.

A longer existence time for NS is relevant to the global existence question for $f = 0$, since it is known that there exists T_c so that any weak Leray solution becomes classical for $t > T_c$

Extending Navier-Stokes interval of existence -II

For $\alpha_0 \geq 0$, define

$$\epsilon = \nu^{-1/2} p_0^{-1/2}, \quad a = \|\hat{v}_0\|_{l^1}, \quad c = \int_{p_0}^{\infty} \|\hat{U}^{(0)}(\cdot, p)\|_{l^1} e^{-\alpha_0 p} dp$$

$$\epsilon_1 = \nu^{-1/2} p_0^{-1/2} \left(2 \int_0^{p_0} e^{-\alpha_0 s} \|\hat{U}(\cdot, s)\|_{l^1} ds + \|\hat{v}_0\|_{l^1} \right)$$

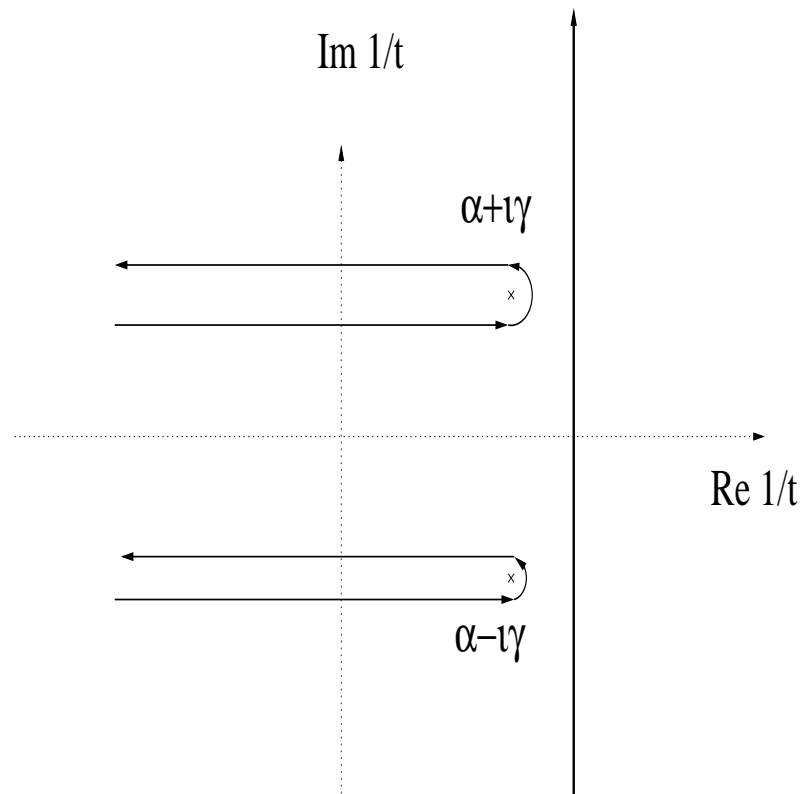
$$b = \frac{e^{-\alpha_0 p_0}}{\sqrt{\nu p_0} \alpha} \int_0^{p_0} \|\hat{U}^* \hat{U} + \hat{v}_0 \cdot \hat{U}\|_{l^1} ds$$

Theorem 4: A smooth solution to 3-D Navier-Stokes equation exists on the interval $[0, \alpha^{-1})$, when $\alpha \geq \alpha_0$ is chosen to satisfy

$$\alpha > \epsilon_1 + 2\epsilon c + \sqrt{(\epsilon_1 + 2\epsilon c)^2 + 4b\epsilon} - \epsilon_1^2$$

Relation of optimal α to NS time singularities

$$\hat{U}(k, p) = \frac{1}{2\pi i} \int_{c_0 - i\infty}^{c_0 + i\infty} e^{p/t} [\hat{v}(k, t) - \hat{v}_0(k)] d \left[\frac{1}{t} \right]$$



Rightmost singularity(ies) of NS solution $\hat{v}(k, t)$ in the $1/t$ plane determines optimal α . γ gives dominant oscillation frequency.

Generalized Laplace-transform representation

Since the Borel domain growth rate α relates to complex right-half $\frac{1}{t}$ NS singularities, the following representation for $n > 1$ is sought:

$$\hat{v}(k, t) = \hat{v}_0(k) + \int_0^\infty e^{-q/t^n} \hat{U}(k, q) dq$$

Note $\hat{U}(\cdot, p) \rightarrow \hat{U}(\cdot, q)$ is an Ecalle' acceleration.

In order that $\hat{U}(\cdot, q)$ has no growth for large q , unless there is a NS singularity for $t \in \mathbb{R}^+$, need to know *a priori* that there is a singularity free sector in the right-half t -plane. This is proved to be true for $f = 0$ and we have the following result:

Theorem 5: For $f = 0$, if NS has a global classical solution, then for all sufficiently large n , $U(x, q) = O(e^{-C_n q^{1/(n+1)}})$ as $q \rightarrow +\infty$, for some $C_n > 0$.

Numerical Solutions to integral equation

We choose the Kida initial conditions and forcing

$$\mathbf{v}_0(\mathbf{x}) = (v_1(x_1, x_2, x_3, 0), v_2(x_1, x_2, x_3, 0), v_3(x_1, x_2, x_3, 0))$$

$$v_1(x_1, x_2, x_3, 0) = v_2(x_3, x_1, x_2, 0) = v_3(x_2, x_3, x_1, 0)$$

$$v_1(x_1, x_2, x_3, 0) = \sin x_3 (\cos 3x_2 \cos x_3 - \cos x_2 \cos 3x_3)$$

$$f_1(x_1, x_2, x_3) = \frac{1}{5} v_1(x_1, x_2, x_3, 0)$$

High Degree of Symmetry makes computationally less expensive

Corresponding Euler problem believed to blow up in finite time;

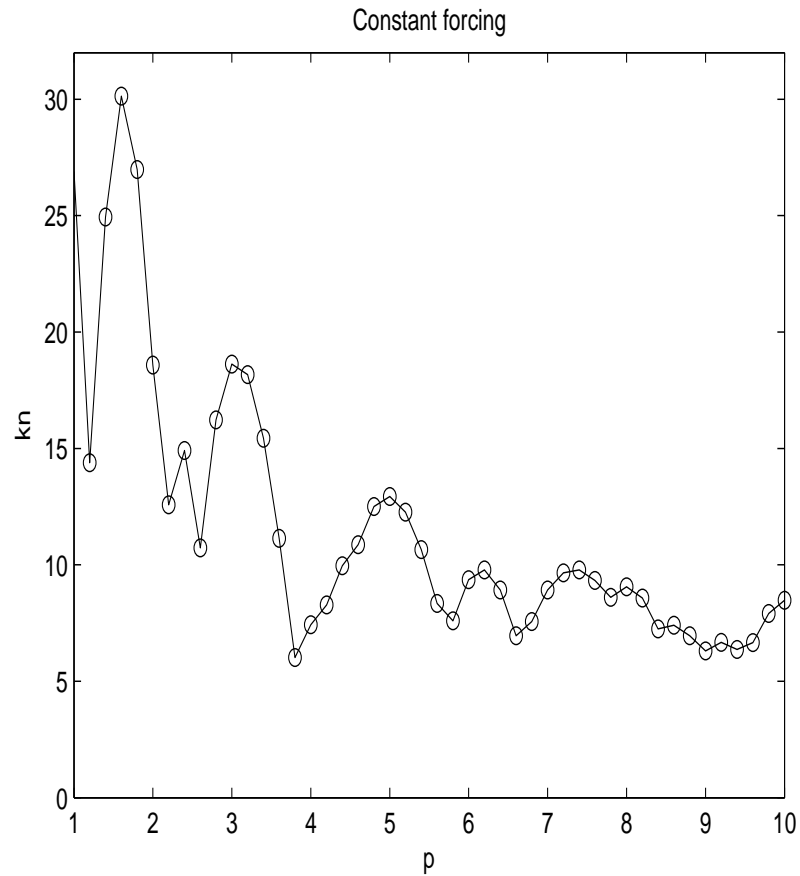
so good candidate to study viscous effects

In the plots, "constant forcing" corresponds to $f = (f_1, f_2, f_3)$ as

above, while zero forcing refers to $f = 0$. Recall sub-exponential

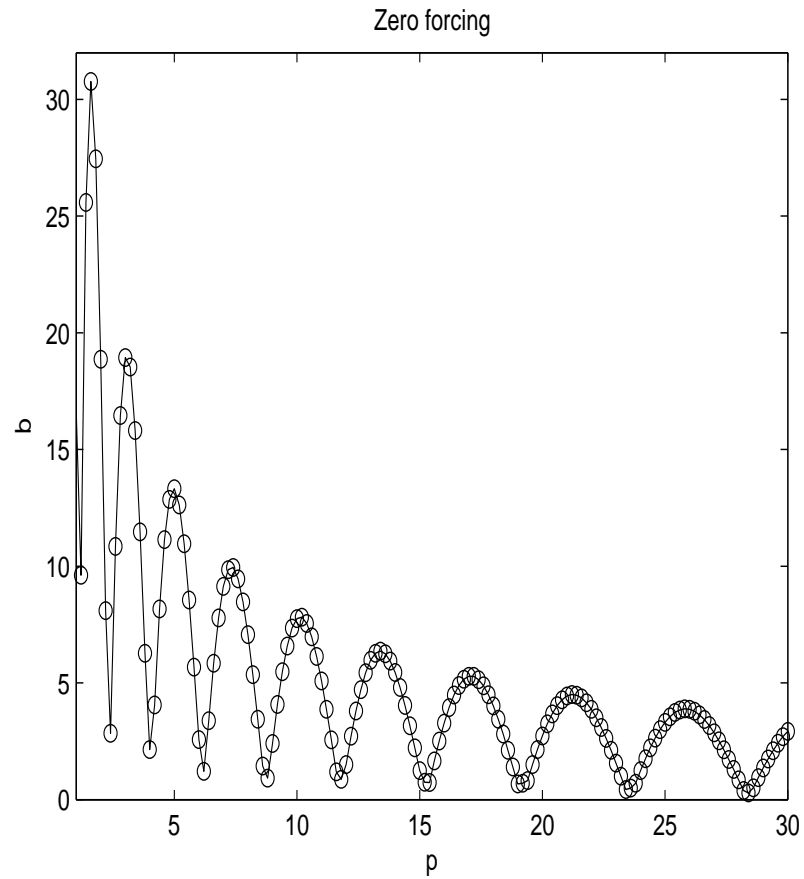
growth in p corresponds to global N-S solution.

Numerical solution to integral equation-plot-1



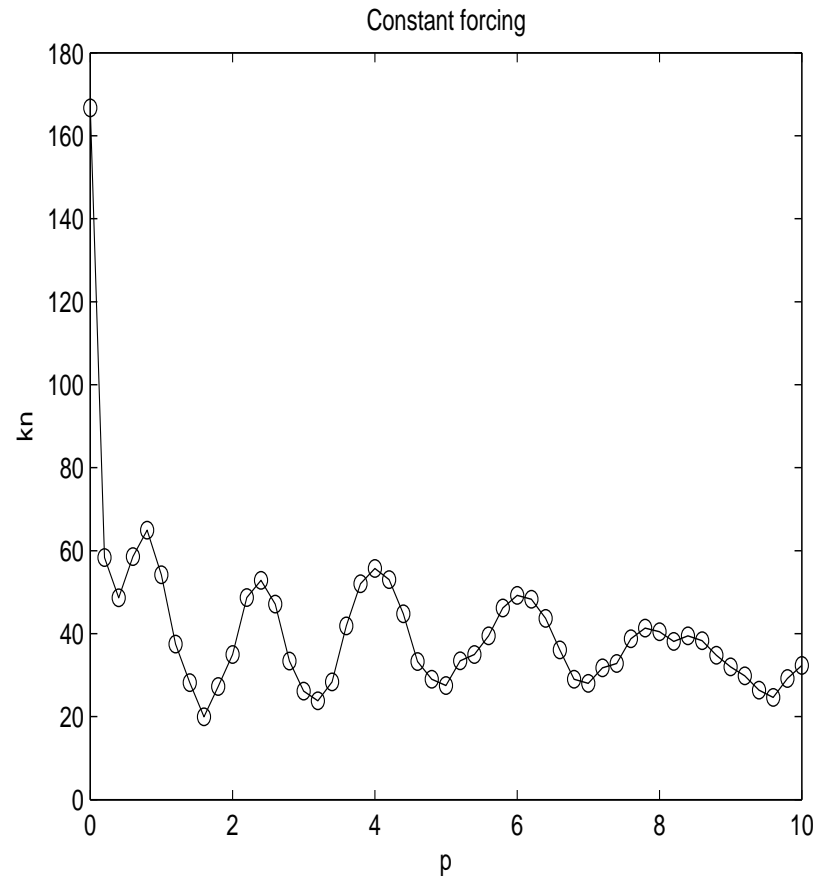
$\|\hat{U}(\cdot, p)\|_{l^1}$ vs. p for $\nu = 1$, constant forcing.

Numerical solution to integral equation-plot-2



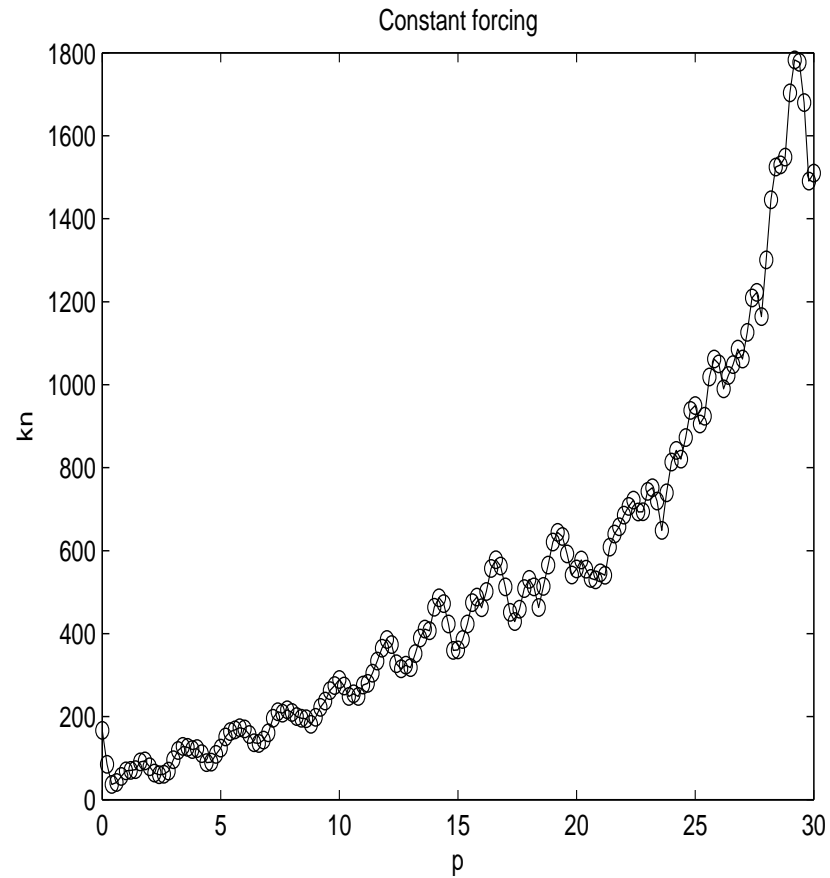
$\|\hat{U}(\cdot, p)\|_{l^1}$ vs. p for $\nu = 1$, no forcing

Numerical solution to integral equation-plot-3



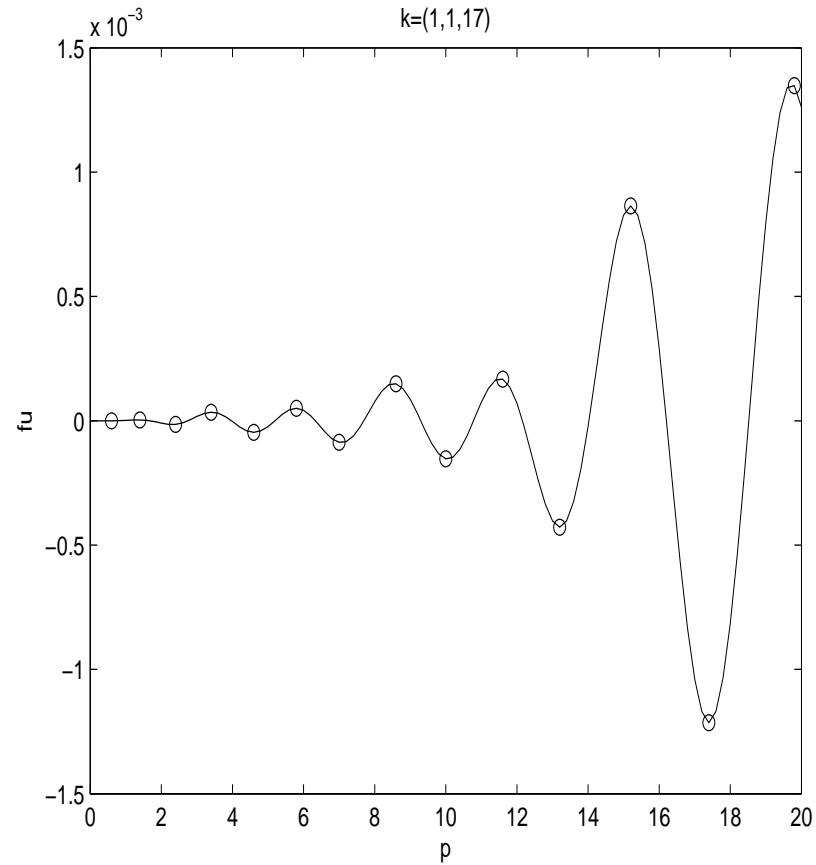
$\|\hat{U}(\cdot, p)\|_{l^1}$ vs. p for $\nu = 0.16$, constant forcing

Numerical solution to integral equation-plot-4



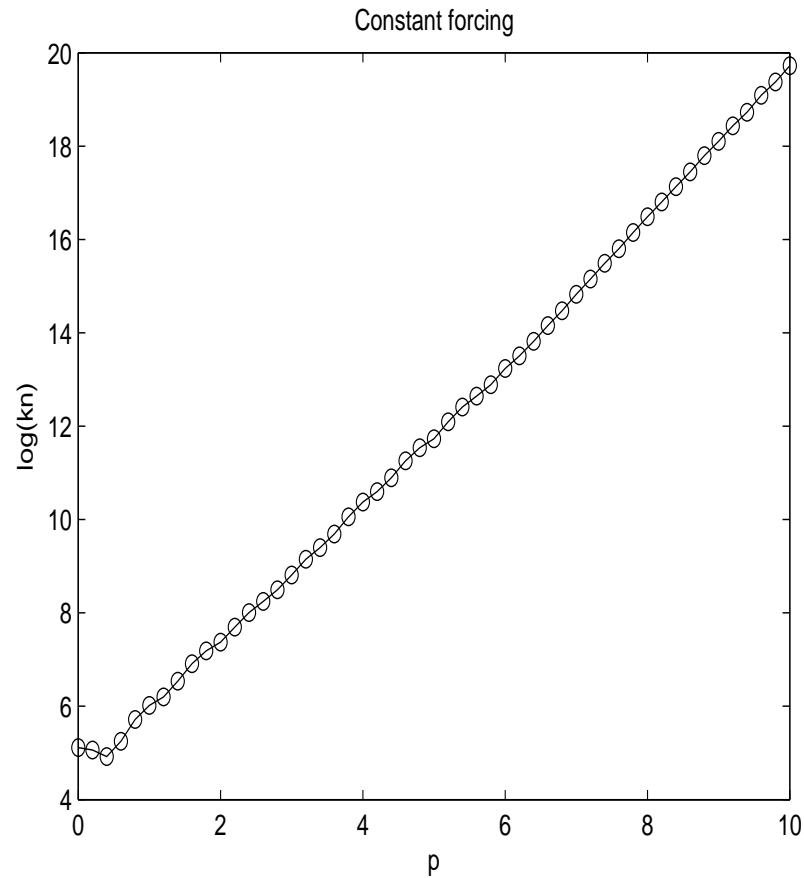
$\|\hat{U}(\cdot, p)\|_{l^1}$ vs. p for $\nu = 0.1$, constant forcing

Numerical solution to integral equation-plot-5



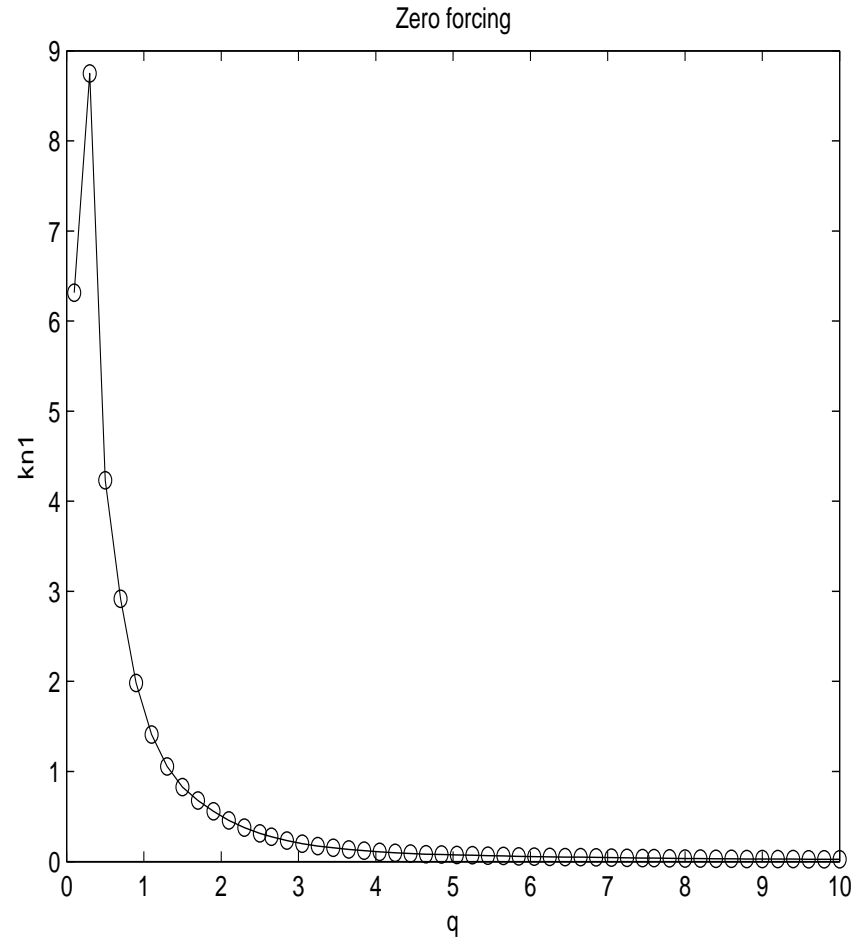
$\hat{U}(k, p)$ vs. p for $k = (1, 1, 17)$, $\nu = 0.1$, no forcing.

Numerical solution to integral equation-plot-6



$\log \|\hat{U}(\cdot, p)\|_{l^1}$ vs. $\log p$ for $\nu = 0.001$, constant forcing

$\|\hat{U}(\cdot, q)\|_{l^1}$ vs. q , $n = 2$, $\nu = 0.1$



Kida I.C. $v_1^{(0)} = \sin x_1 (\cos 3x_2 \cos x_3 - \cos x_2 \cos 3x_3)$

Other components from cyclic relation:

$$v_1^{(0)}(x_1, x_2, x_3) = v_1^{(0)}(x_3, x_1, x_2) = v_3^{(0)}(x_2, x_3, x_1)$$

Extending Navier-Stokes interval of existence

For $\alpha_0 \geq 0$, define

$$\epsilon_1 = \nu^{-1/2} q_0^{-1+1/(2n)}, \quad c = \int_{q_0}^{\infty} \|\hat{U}^{(0)}(\cdot, q)\|_{l^1} e^{-\alpha_0 q} dq$$

$$\epsilon_1 = \nu^{-1/2} q_0^{-1+1/(2n)} \left(2 \int_0^{q_0} e^{-\alpha_0 s} \|\hat{U}(\cdot, s)\|_{l^1} ds + \|\hat{v}_0\|_{l^1} \right)$$

$$b = \frac{e^{-\alpha_0 q_0}}{\sqrt{\nu} q_0^{1-1/(2n)} \alpha} \int_0^{q_0} \|\hat{U}_*^* \hat{U} + \hat{v}_0 \cdot \hat{U}\|_{l^1} ds$$

Theorem 6: A smooth solution to 3-D Navier-Stokes equation exists in the $\|\cdot\|_{l^1}$ space on the interval $[0, \alpha^{-1/n})$, when $\alpha \geq \alpha_0$ is chosen to satisfy

$$\alpha > \epsilon_1 + 2\epsilon c + \sqrt{(\epsilon_1 + 2\epsilon c)^2 + 4b\epsilon - \epsilon_1^2}$$

Remark: If q_0 is chosen large enough, ϵ, ϵ_1 is small when computed solution in $[0, q_0]$ decays with q . Then α can be chosen rather small.

Other problems where approach is applicable

- Navier-Stokes with temperature field (Boussinesq approximation)

- Fourth order Parabolic equations of the type:

$$u_t + \Delta^2 u = N[u, Du, D^2 u, D^3 u]$$

- Magneto-hydrodynamic equation with certain approximations.

- For some PDE problems with finite-time blow-up, blow-up time related to exponent α of exponential growth of Integral equation as $n \rightarrow \infty$.

Conclusions

We have shown how Borel summation methods provides an alternate existence theory for PDE Initial value problems like N-S. With this integral equation (IE) approach, the PDE global existence is implied if known solution to IE has subexponential growth at ∞ .

The solution to integral equation in a finite interval can be computed numerically with rigorously controlled errors.

Integral equation in a suitable accelerated variable q will decay exponentially for unforced N-S equation, unless there is a real time singularity of PDE solution.

The computation over a finite $[0, q_0]$ interval gives a refined bound on exponent α at ∞ , and hence a longer existence time $[0, \alpha^{-1/n})$ to 3-D Navier-Stokes.

Approach is applicable to a wide class of other PDE initial value problems.